

## Linear Smoothing: Conclusion and Extensions V

### Example: Height of Girls

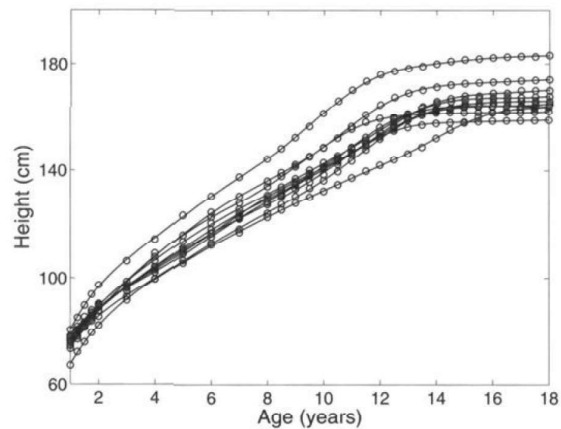


Figure 1.1. The heights of 10 girls measured at 31 ages. The circles indicate the unequally spaced ages of measurement.

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## Linear Smoothing: Conclusion and Extensions VI

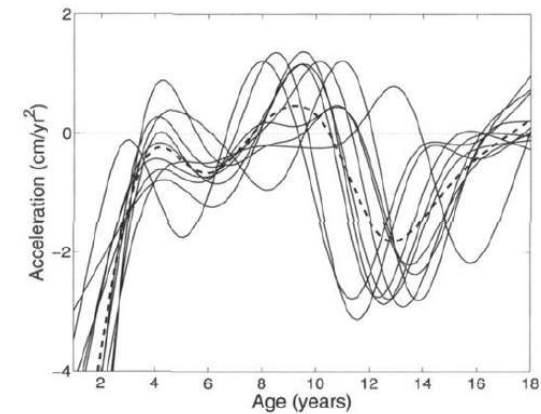


Figure 1.2. The estimated accelerations of height for 10 girls, measured in centimeters per year. The heavy dashed line is the cross-sectional mean, and is a rather poor summary of the curves.

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## Functional PCA I

### Definition (Mean and variance functions)

Consider the functions  $\{\mu_j(t)\}_{j=1, \dots, J}$  that are observed instances of the random function  $s(t)$ , the **mean function** is the average of the functions:

$$\mathbb{E}[s(t)] = \bar{\mu}(t) = \frac{1}{J} \sum_{j=1}^J \mu_j(t)$$

and the **variance function** is:

$$\text{Var}[s(t)] = \frac{1}{J-1} \sum_{j=1}^J (\mu_j(t) - \bar{\mu}(t))^2$$

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## Functional PCA II

### Example (Height of Girls)

$$\overline{\text{Height}}(t) = \frac{1}{10} \sum_{i=1}^{10} \text{Height}_i(t)$$

$$\text{Var}_{\text{Height}}(t) = \frac{1}{10-1} \sum_{i=1}^{10} (\text{Height}_i(t) - \overline{\text{Height}}(t))^2$$

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## Functional PCA III

FPCA, Principal Component Analysis for functions:

- We compute the mean  $\bar{\mu}(t)$  and subtract it to each curve:

$$\tilde{\mu}_j(t) = \mu_j(t) - \bar{\mu}(t)$$

- Let  $v(t_1, t_2) = \mathbb{E}[\tilde{\mu}(t_1) \tilde{\mu}(t_2)]$  be the sample covariance function, it can be estimated by:

$$\hat{v}(t_1, t_2) = \frac{1}{J} \sum_{j=1}^J \tilde{\mu}_j(t_1) \tilde{\mu}_j(t_2)$$

- An eigencurve  $u(t)$  is then computed such that:

$$\forall t_1, \int \hat{v}(t_1, t) u(t) dt = \lambda u(t_1) \quad \text{subject to} \quad \int u(t)^2 dt = 1$$

## Functional PCA IV

- A simple approach is to discretise the functions  $\tilde{\mu}_j(t)$  to a fine grid of  $N$  sites equally spaced on the time line. This allows to treat these functions as finite dimensional vectors and standard PCA can be applied to estimate the eigenvectors.
- The continuous principal component  $u(t)$  is recovered by interpolating the discrete eigenvector.
- The choice of interpolation method does not matter when recovering the eigencurve from the eigenvector when the space between the  $N$  sampling sites is small.
- This approach is the earliest approach to **functional principal component analysis**.