

### 3 Example: Galerkin Formulation of Poisson's Equation

We consider the Poisson equation:

$$u''(x) = -f(x) \quad 0 < x < 1$$

with boundary conditions  $u(0) = u(1) = 0$ . We want to estimate the trial solution

$$\tilde{u}(x) = \sum_{i=1}^N \alpha_i \Phi_i(x)$$

using the Galerkin method and using the piecewise linear functions (cf. figure 1) as basis:

$$\Phi_j(x) = \begin{cases} \frac{1}{\Delta}(x - x_{j-1}) & \text{for } x_{j-1} \leq x \leq x_j \\ \frac{1}{\Delta}(x_{j+1} - x) & \text{for } x_j \leq x \leq x_{j+1} \\ 0 & \text{otherwise} \end{cases} \quad (3)$$

with  $\Delta = x_{j+1} - x_j$ ,  $\forall j$ , with  $0 = x_0 < x_1 < x_2 < \dots < x_N < x_{N+1} = 1$ .

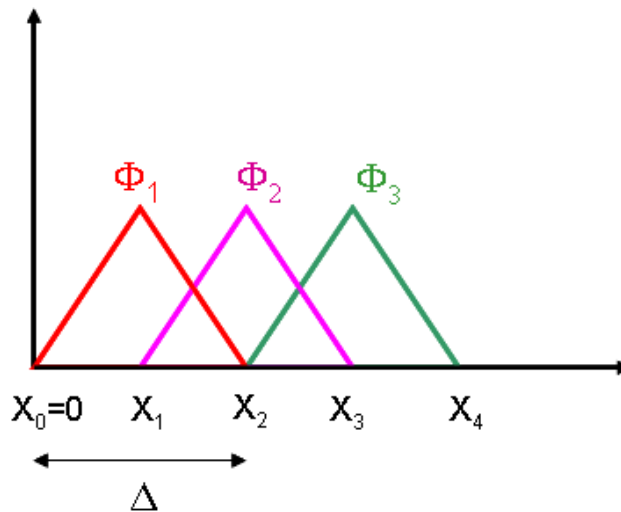


Figure 1: Linear basis functions.

One can notice that

$$\Phi_j(x_i) = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{otherwise} \end{cases}$$

or  $\Phi_j(x_i) = \delta_{ij}$  (Kronecker's delta).

Considering the boundary conditions, we do have  $\Phi_j(0) = \Phi_j(1) = 0$ ,  $\forall j = 1 \dots N$ , hence the boundary conditions are verified for the trial solution  $\tilde{u}(0) = \tilde{u}(1) = 0$ .

#### 3.1 Residual function

The residual function is:

$$\begin{aligned} R(x; \alpha) &= \tilde{u}''(x) + f(x) \\ &= \sum_{i=1}^N \alpha_i \Phi_i''(x) + f(x) \end{aligned} \quad (4)$$

#### 3.2 Solving with Galerkin method

We need to find  $\alpha$  such that:

$$\int_0^1 R(x; \alpha) \Phi_j(x) dx = 0 \quad \forall j$$

Replacing the residual by its expression (4), we have

$$\int_0^1 \left( \sum_{i=1}^N \alpha_i \Phi_i''(x) + f(x) \right) \Phi_j(x) dx = 0 \quad \forall j$$

or

$$\sum_{i=1}^N \alpha_i \int_0^1 \Phi_i''(x) \Phi_j(x) dx = - \int_0^1 f(x) \Phi_j(x) dx \quad \forall j \quad (5)$$

### 3.2.1 Consider the integral $\int_0^1 \Phi_i''(x) \Phi_j(x) dx$

We can solve it by integration by parts:

$$\int_0^1 \Phi_i''(x) \Phi_j(x) dx = \left[ \Phi_i'(x) \Phi_j(x) \right]_0^1 - \int_0^1 \Phi_i'(x) \Phi_j'(x) dx$$

We have the first term  $\left[ \Phi_i'(x) \Phi_j(x) \right]_0^1 = 0$  since  $\Phi_j(0) = \Phi_j(1) = 0$ ,  $\forall j$ . From equation (3), we can compute the derivative of  $\Phi_j$ :

$$\Phi_j'(x) = \begin{cases} \frac{1}{\Delta} & \text{for } x_{j-1} \leq x \leq x_j \\ \frac{-1}{\Delta} & \text{for } x_j \leq x \leq x_{j+1} \\ 0 & \text{otherwise} \end{cases}$$

We can note that  $\Phi_j'$  is discontinuous at  $x_j, x_{j-1}$  and  $x_{j+1}$ . We compute the term  $\int_0^1 \Phi_i'(x) \Phi_j'(x) dx$  in all cases:

- if  $i = j$  then

$$\int_0^1 \Phi_j'(x) \Phi_j'(x) dx = \frac{2}{\Delta}$$

- if  $i = j - 1$  or  $i = j + 1$

$$\int_0^1 \Phi_{j-1}'(x) \Phi_j'(x) dx = \frac{-1}{\Delta}$$

- otherwise

$$\int_0^1 \Phi_i'(x) \Phi_j'(x) dx = 0$$

### 3.2.2 Solving equation (5)

Using linear algebra, we store all the values

$$\langle f, \Phi_j \rangle = \int_0^1 f(x) \Phi_j(x) dx$$

into a vector  $\mathbf{b}$  (i.e. such that the  $j$  component of  $\mathbf{b}$  is  $b_j = \langle f, \Phi_j \rangle$ ). All the values  $\langle \Phi_i', \Phi_j' \rangle = \int_0^1 \Phi_i'(x) \Phi_j'(x) dx$  are stored in a  $N \times N$  matrix  $\mathbf{A}$  such that its components are defined by  $a_{ij} = \langle \Phi_i', \Phi_j' \rangle$ .

Then we can rewrite equation (5):

$$\mathbf{A}\boldsymbol{\alpha} = \mathbf{b}$$

or

$$\frac{1}{\Delta} \begin{bmatrix} 2 & -1 & 0 & \cdots & 0 \\ -1 & 2 & -1 & \ddots & 0 \\ 0 & -1 & 2 & \ddots & \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & & 0 & -1 & 2 \end{bmatrix} \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_N \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_N \end{pmatrix}$$

In this linear equation, the unknown we are looking for is  $\boldsymbol{\alpha}$  and it can easily be computed:

$$\hat{\boldsymbol{\alpha}} = \mathbf{A}^{-1}\mathbf{b}$$