

# The Security $\pi$ -calculus and Non-interference

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- Background
- The Security  $\pi$ -calculus
- Types
- Behavioural Equivalences
- Non-Interference Results

Work in progress by EU Global Computing projects Mikado/ Myths

# Background

- Control of information flow in systems  
cf. Denning, Goguen, Mesegeur
- **Integrity:** No High-to-Low information flow:  
High (security) level users should not be able to send high-level information to Low level users.  
(No Trojan horses)
- **Non-interference:** Formal property of systems which ensures their integrity.

# High-to-Low Information Flow

**Explicit:** H sends high-level data (my visa no) to L

**Implicit:** H sends low-level data to L

H, L could have prearranged interpretation:

- 0 - Boss is in town
- 1 - Boss is away

**Implicit:** H may rendez-vous with L

- H turns up - Boss is away
- H absent - Boss is in town

# How to Avoid H-to-L Information Flow

H can not send any data to L

Q?: What kind of data can L send to H ?

Q?: How can rendez-vous's be managed ?

More General Q?: How can we SPECIFY behaviour of system which will ensure no H-to-L information flow ?

ANSWER: Codify using **Types** cf. Volpano et al.

A system is **safe** if it can be typechecked

# Safe Systems

- How do we **prove** safe systems contain no H-to-L information flow?
- Introduce **Interference-Freeness**: Formal verifiable concept, which informally implies no H-to-L information flow
- Main Theorem:  $\boxed{S}$  is typeable (using my type system) implies  $\boxed{S}$  is interference-free

# Interference-Freeness

## Requirements:

- concept of **High-level process** (specified using Type system)
- concept of **behavioural equivalence**  $\simeq_\sigma$ , relativised to security levels  $\sigma$ , ( $= \text{bot}, \dots, \text{top}$ )

Definition:  $\boxed{S}$  is **Interference-Free** if

$$\boxed{S} \mid H \simeq_{\text{bot}} \boxed{S} \mid K$$

for all **High-level processes**  $H, K$ .

# Remainder of Talk

- Language:  $\pi$ -calculus
- Types: input/output types, relativised to security levels
- Behavioural Equivalences  $\simeq_\sigma$ : based on testing

# The Security $\pi$ -calculus (asynchronous)

channels = resources = read once variables

- $u?(x : T) P$  - patterned input on channel  $u$   
to resource  $u$
- $u!\langle v \rangle$  - polyadic output on channel  $u$   
from resource  $u$   
 $v$  a tuple of values - may be **channels**
- $P \mid Q$  - concurrent code
- $\text{if } u = v \text{ then } P \text{ else } Q$  - value testing
- $(\text{new } n : T) P$  - generation of new names
- $*P, \mathbf{0}$  - iteration and termination



# Reduction Semantics

Same as ever (for  $\pi$  hackers):

$$\text{(com)} \quad a!\langle v \rangle \mid a?(x : A) P \mapsto (P[v/x])$$

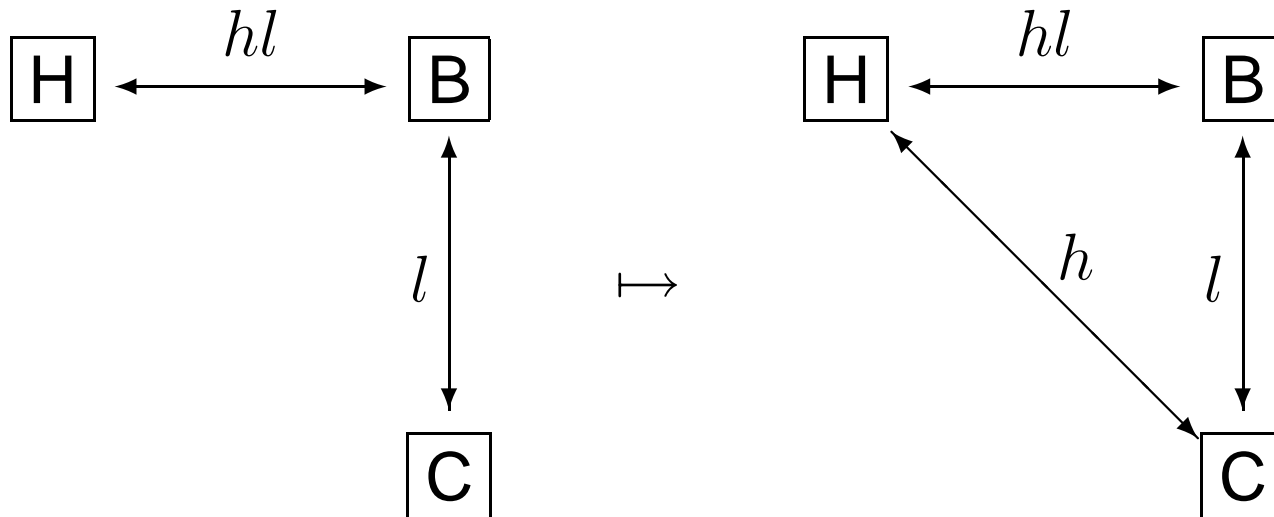
$$\text{(str)} \quad \frac{P \equiv Q, P \mapsto P', P' \equiv Q'}{Q \mapsto Q'}$$

$$\text{(cong)} \quad \frac{P \mapsto P'}{P \mid Q \mapsto P' \mid Q}$$

(etc.)

# Reduction Semantics

Dynamic creation of communication links:



Interface between **H** and **L** processes must be managed

# Security Levels

A (static) complete lattice of security levels, *SL*.

- bot: lowest security level
  - the great unwashed
  - processes arriving off the web
  - processes at this level offer no security
- top: highest security level
  - the chosen few
  - processes owned by superuser on local machine
- $\text{bot} \leq \textit{moderate} \leq \text{top}$ :
  - processes originating on local area network
  - processes which have demonstrated some reliability

*SL* may have an arbitrary complicated structure.

# Types - graded read/write capabilities

$Type_\sigma$ : Type for values accessible at security level  $\sigma$

$$\{w_\sigma\langle A \rangle, r_{\rho_1}\langle B_1 \rangle, r_{\rho_2}\langle B_2 \rangle, \dots, r_{\rho_k}\langle B_k \rangle\}$$

provided

- $\sigma \leq \rho_i$  - no write ups
- $A \in Type_\sigma$ ,  $B_i \in Type_{\rho_i}$
- $A$  *subtype*  $B_i$

Example:

- **Yes:**  $\{w_{\text{bot}}\langle \mathbf{int} \rangle, r_{\text{bot}}\langle \mathbf{int} \rangle, r_{\text{top}}\langle \mathbf{int} \rangle\}$  - multi-level type
- **No:**  $\{w_{\text{top}}\langle \mathbf{int} \rangle, r_{\text{bot}}\langle \mathbf{int} \rangle, r_{\text{top}}\langle \mathbf{int} \rangle\}$
- **No:**  $\{w_{\text{bot}}\langle w_{\text{bot}}\langle \mathbf{int} \rangle \rangle, r_{\text{bot}}\langle \dots \rangle, r_{\text{top}}\langle w_{\text{bot}}\langle \mathbf{int} \rangle \rangle\}$

# Typing Systems non-stop

Type Environment  $\Gamma = u_1 : A_1, \dots, u_k : A_k$

- $\Gamma \vdash P$  -  $P$  well-typed wrt  $\Gamma$ , **ignoring security levels**
- $\Gamma \vdash_\sigma P$  -  $P$  well-typed, using **at most** level  $\sigma$  resources
- $\Gamma \vDash^\sigma P$  -  $P$  well-typed, using **at least** level  $\sigma$  resources
- $\Gamma \vdash_{r\sigma} P$  -  $\dots$ , **reading** from **at most** level  $\sigma$  resources
- $\Gamma \vDash^{w\sigma} P$  -  $\dots$ , **writing** to **at least** level  $\sigma$
- $\dots$

**Thm: Subject Reduction:**  $\Delta \Vdash P$  and  $P \mapsto^* Q$  implies  $\Delta \Vdash Q$

# Type Inference

$$\frac{\begin{array}{l} \text{(LT-IN)} \\ \Gamma, X : A \vdash_{\sigma} P \\ \Gamma \vdash u : r_{\delta} \langle A \rangle \end{array}}{\Gamma \vdash_{\sigma} u?(X : A) P} \quad \delta \preceq \sigma \qquad \frac{\begin{array}{l} \text{(LT-OUT)} \\ \Gamma \vdash v : A \\ \Gamma \vdash u : w_{\delta} \langle A \rangle \end{array}}{\Gamma \vdash_{\sigma} u! \langle v \rangle} \quad \delta \preceq \sigma$$

$$\frac{\begin{array}{l} \text{(T-EQ)} \\ \Gamma \vdash u : A, v : B \\ \Gamma \Vdash Q \\ \Gamma \sqcap \{u : B, v : A\} \Vdash P \end{array}}{\Gamma \Vdash \text{if } u = v \text{ then } P \text{ else } Q} \qquad \frac{\begin{array}{l} \text{(T-NEW)} \\ \Gamma, a : A \Vdash P \end{array}}{\Gamma \Vdash (\text{new } a : A) P}$$

# Examples

$\boxed{H} \Leftarrow \mathbf{lh}?(x) x!\langle 3pm \rangle$

$\boxed{L} \Leftarrow \mathbf{lh}!\langle cvt \rangle cvt?(i) broadcast(i)$

If  $\mathbf{lh}$  is  $w_{\text{bot}}\langle \dots \rangle$ ,  $r_{\text{top}}\langle \dots \rangle$  then  $\Gamma \not\vdash L \mid H$

$L \mid H$  contains information flow

$TrH \Leftarrow \mathbf{h}?(x) .\text{if } x = \mathbf{boss} \text{ then } tr_1!\langle \rangle \text{ else } tr_2!\langle \rangle$

If  $\mathbf{h}$  high,  $tr_i$  low, then  $TrH$  can not be High-level

$TrH$  represents a trojan horse

# Safe Systems at last

**Definition:**  $\boxed{S}$  is  $\Gamma$ -safe if  $\Gamma \vdash_{r_{\text{bot}}} S$

They can only read from low-level channels

**Claim:** If  $\boxed{S}$  is  $\Gamma$ -safe then

$$\boxed{S} \mid H \simeq_{\text{bot}} \boxed{S} \mid K \quad \text{informal}$$

for all High-level processes  $H, K$ .

**Definition:**  $H$  is a High-level process if  $\Gamma \vdash^{w_{\text{top}}} H$

They can only write to high-level channels



# Behavioural Equivalences

Idea:  $\boxed{S} \simeq_\sigma \boxed{U}$  at level  $\sigma$ , if no observer running at level at most  $\sigma$  can not distinguish between  $S$  and  $U$ .

- An observation of  $S$  by  $O$  is a sequence  $O \mid S \mapsto O_1 \mid S_1 \dots \mapsto O_n \mid S_n \mapsto \dots$
- Successful if some  $O_k$ , can report success
- $S$  **may**  $O$  if there is some successful observation of  $S$  by  $O$
- $S$  **must**  $O$  if every observation of  $S$  by  $O$  is successful

Definition:  $\Gamma \triangleright_\sigma \boxed{S} \simeq_{may} \boxed{U}$  if for every  $\Gamma \vdash_\sigma O$ ,  
 $S$  **may**  $O$  if and only if  $U$  **may**  $O$

$\Gamma \triangleright_\sigma \boxed{S} \simeq_{must} \boxed{U}$  if .....

# Non-Interference

Idea:  $\boxed{S}$  is interference-free if low-level observers/users can not detect the presence/absence of high-level users in  $S$ .

Definition:  $\boxed{S}$  is mayIntFree if

$$\Gamma \triangleright_{\text{bot}} S \mid H \simeq_{\text{may}} S \mid K$$

for all High-level process  $H, K$

**NonInterference for Free:**

**Thm:** If  $S$  is  $\Gamma$ -safe ( $\Gamma \vdash_{r_{\text{bot}}} S$ ) then  $S$  is mayIntFree

# Examples

Assume  $H, K$  high-level ( $\Gamma \vdash^{w\text{top}} H, K$ )  
 $S$  safe ( $\Gamma \vdash_{r\text{bot}} S$ )

$$\boxed{\mathbf{H}} = \mathbf{h?}(x) \text{ if } x = \mathbf{boss} \text{ then } \text{tr}_1! \langle \rangle \text{ else } \text{tr}_2! \langle \rangle$$

$$\boxed{\mathbf{K}} = \mathbf{h?}(x) \text{tr}_1! \langle \rangle$$

$\Gamma \triangleright_{\text{bot}} S \mid H \simeq_{\text{may}} S \mid K$  because write on  $\text{tr}_i$  must be high

$$\boxed{\mathbf{H}} = \mathbf{h?}(x) \text{ if } x = \mathbf{boss} \text{ then } \text{tr}_1?() \text{ else } \text{tr}_2?()$$

$$\boxed{\mathbf{K}} = \mathbf{h?}(x) \text{tr}_1?()$$

$\Gamma \triangleright_{\text{bot}} S \mid H \simeq_{\text{may}} S \mid K$  because communication is asynchronous

# Example: Multi-level types

$\Gamma$  maps ml to  $\{w_{\text{bot}}\langle \dots \rangle, r_{\text{bot}}\langle \dots \rangle, r_{\text{top}}\langle \dots \rangle\}$  multi-level type

$\boxed{\mathbf{S}}$  = ml! $\langle a \rangle$  | ml?( $x$ )  $x!$  $\langle \rangle$

$\Gamma \triangleright_{\text{bot}} S \mid H \simeq_{\text{may}} S \mid K$  because  $S$  is safe

**BUT:**  $\Gamma \triangleright_{\text{bot}} S \mid H \not\approx_{\text{must}} S \mid K$

eg with  $H = \mathbf{0}$  and  $K = \text{ml?}(x : \mathbf{B}) \mathbf{0}$

observer  $a?() \omega!\langle \rangle$  sees a difference

**Thm:** Suppose  $\Gamma$  uses only single-level types.

If  $S$  is  $\Gamma$ -safe then it is mustIntFree

# Wrap up

**Thesis:** Potential H-to-L information flow in concurrent systems can be detected by type systems

**Questions:**

- How difficult is type inference?
- How restrictive is the type system?
- Can types be extended to distributed systems?

**Technical Details:** Sussex technical reports