

On the Semantics of Markov Automata

Matthew Hennessy

(joint work with Yuxin Deng)

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1/34

Adding time to process descriptions

Pervasive:

- ▶ all actions have duration: $a^{3.5}.P + \mathbf{delay}(1.3).Q \mid b^{2.1}.R$
- ▶ Semantic theory very sensitive to timing

Maximal progress:

- ▶ only passage of time has duration
- ▶ all other actions are instantaneous
- ▶ time only passes when no more actions are possible:
 $\mathbf{delay}(d_1).Q_1 + b.(\mathbf{delay}(d_2).Q_2 + c.R) \mid \bar{b}.\bar{a}.P$
- ▶ Semantic theory does not measure passage of time directly



3/34

Nature of time

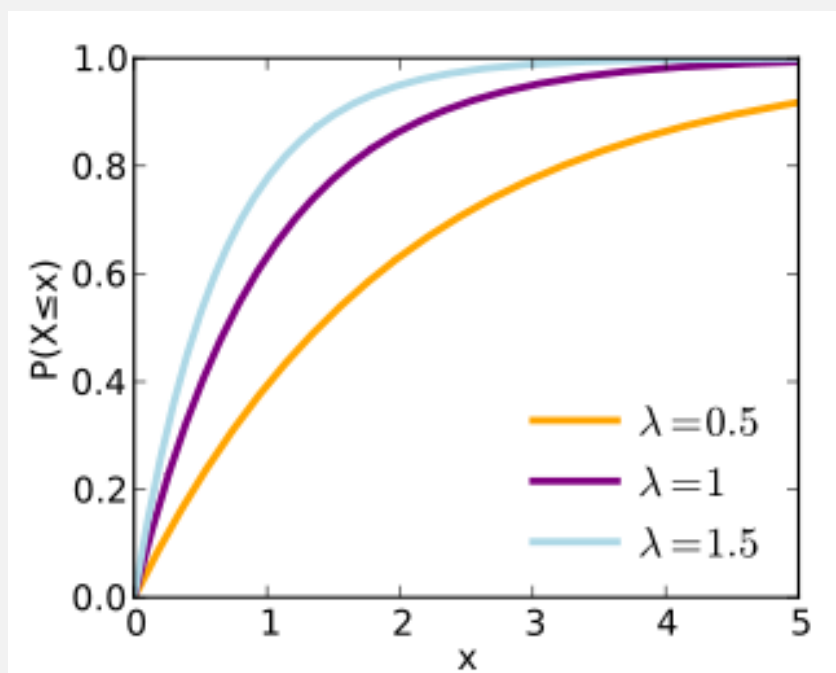
- ▶ discrete time: $\mathbf{delay}(3).Q_1 + b.(\mathbf{delay}(2).Q_2 + c.R) \mid \bar{b}.\bar{a}.P$
- ▶ real-time:
 $\mathbf{delay}(3.223).Q_1 + b.(\mathbf{delay}(1.567).Q_2 + c.R) \mid \bar{b}.\bar{a}.P$
- ▶ probabilistic time:
 $\mathbf{delay}(d_1).Q_1 + b.(\mathbf{delay}(d_2).Q_2 + c.R) \mid \bar{b}.\bar{a}.P$

Timing of events $\mathbf{delay}(d_i)$ governed by probability distributions d_i

Poisson processes

Probability that event has happened by time x :

$$P(x) = (1 - e^{-\lambda x})$$



Poisson processes

$$P(x) = (1 - e^{-\lambda x})$$

Rates:

Characteristics completely determined by *rate* λ

- ▶ Memoryless: useful for interpreting parallel construct:
delay(λ). Q_1 | **delay**(β). Q_2
- ▶ Race law: **delay**(λ). Q_1 + **delay**(β). Q_2
 - ▶ probability that Q_1 wins: $\frac{\lambda}{\lambda+\beta}$
 - ▶ probability that Q_2 wins: $\frac{\beta}{\lambda+\beta}$



Markov automata

$$\langle S, \text{Act}_\tau, \rightarrow, \mapsto, \rangle,$$

where

- (i) S is a set of states
- (ii) Act_τ is a set of transition labels, with distinguished element τ
- (iii) the relation \mapsto is a subset of $S \times (\mathbb{R}^+ \cup \{\delta\}) \times \mathcal{D}(S)$

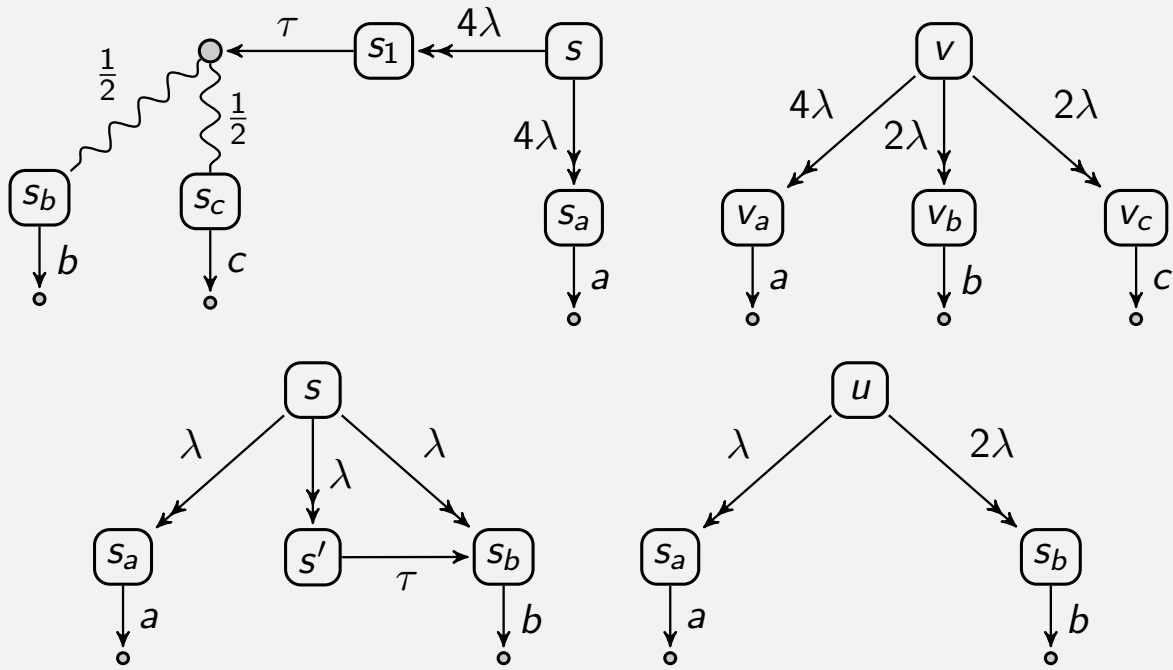
satisfying

- (a) $s \xrightarrow{\mathbf{d}} \Delta$ implies $s \not\xrightarrow{\tau} \mathbf{d} = \lambda \text{ or } \delta$
- (b) $s \xrightarrow{\delta} \Delta_1$ and $s \xrightarrow{\delta} \Delta_2$ implies $\Delta_1 = \Delta_2$

- ▶ $s \xrightarrow{\lambda} \Delta$: definite time delay, governed by rate $\lambda \in \mathbb{R}^+$
- ▶ $s \xrightarrow{\delta} \Delta$ indefinite time delay
- ▶ (a) is maximal progress

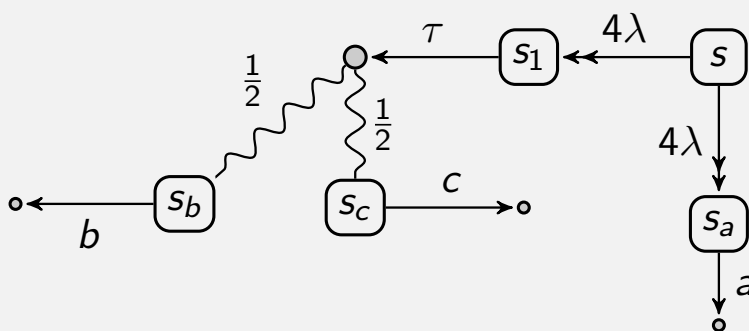


Examples

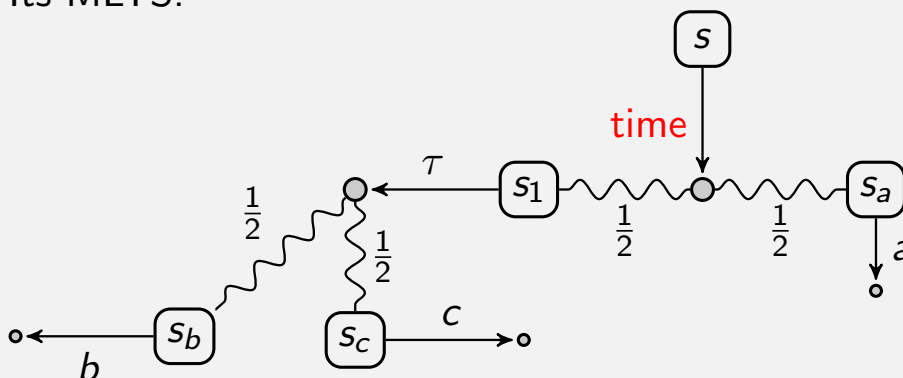


From time to probabilities

An MA:

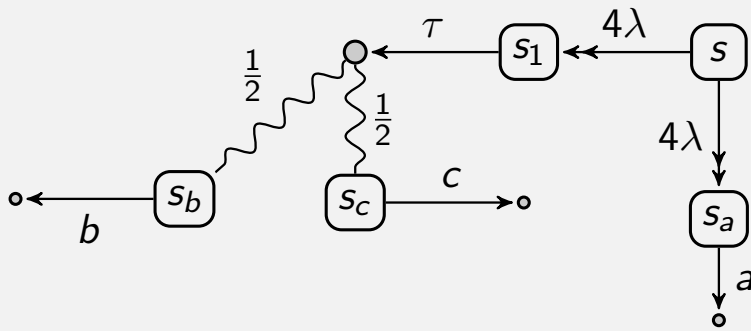


Its MLTS:

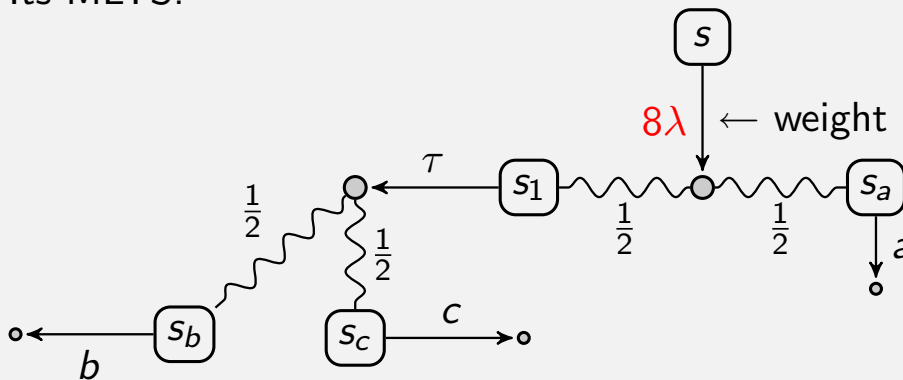


From time to probabilities

An MA:

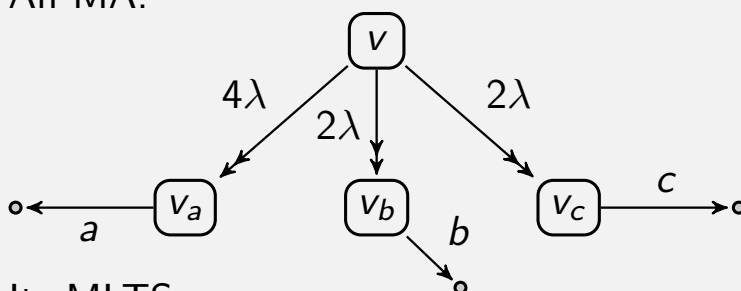


Its MLTS:

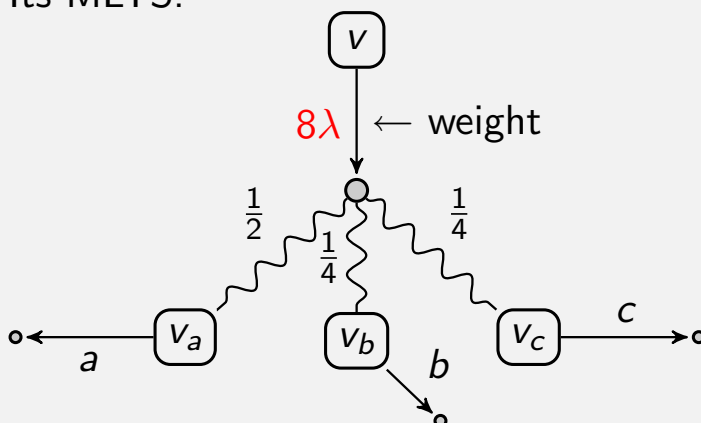


From time to probabilities

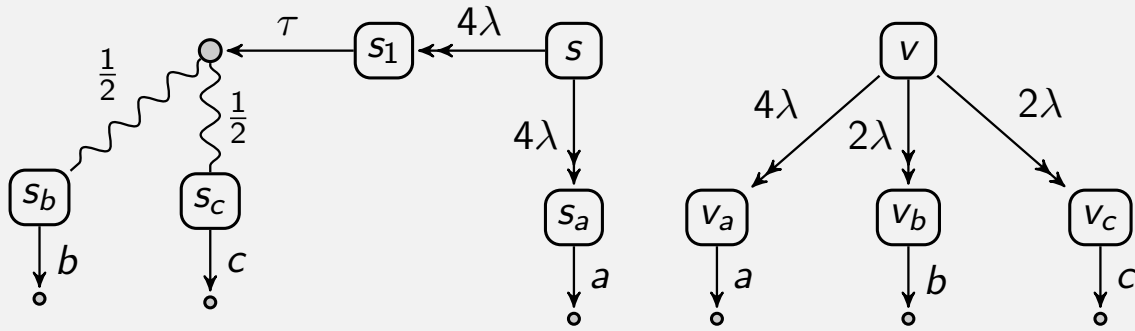
An MA:



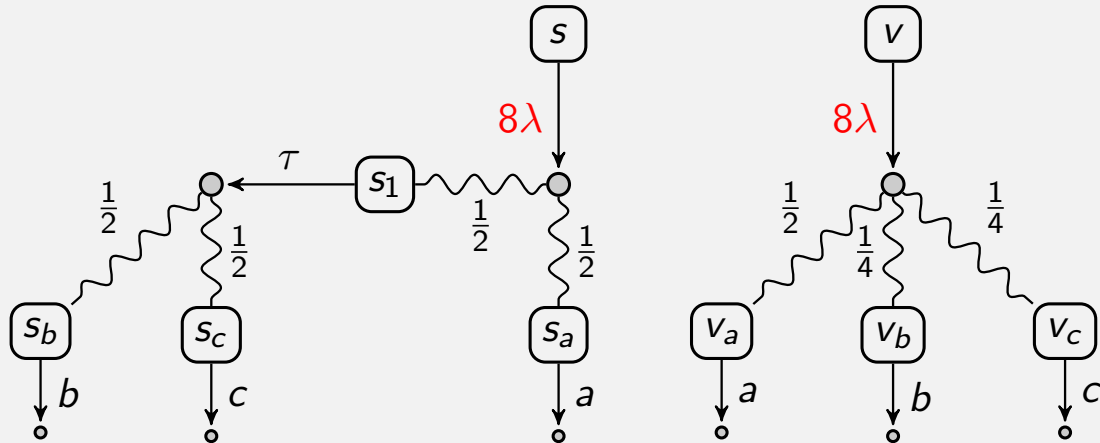
Its MLTS:



Semantically equivalent?

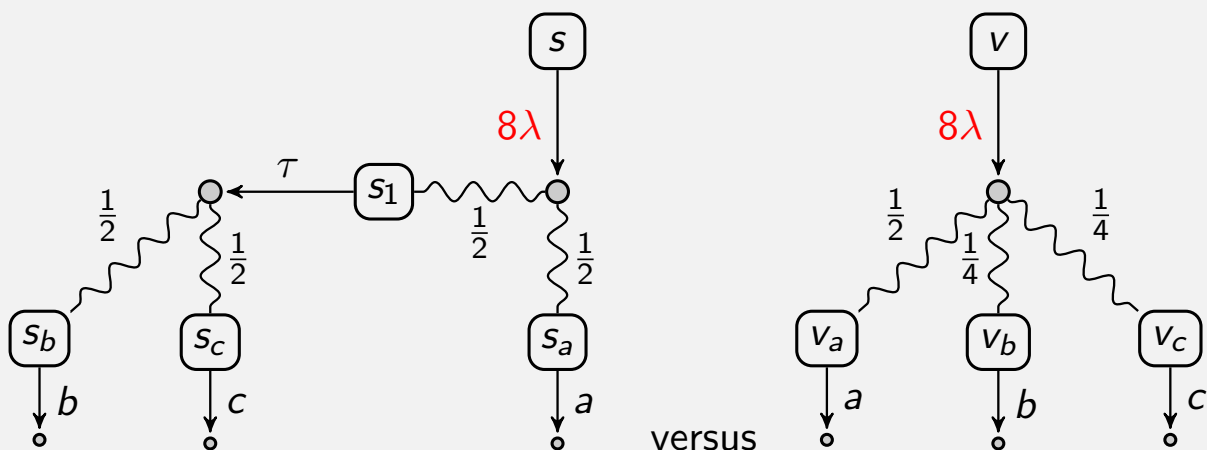


Semantically equivalent MLTSs?:



13/34

Semantically equivalent?



- ▶ Not according to existing definitions of *bisimulation equivalence*
- ▶ Can a revised version of *bisimulation equivalence* be formulated?
- ▶ Is this revision justifiable?



14/34

Lifting relations

From $\mathcal{R} \subseteq S \times \mathcal{D}(S)$, to $\text{lift}(\mathcal{R}) \subseteq \mathcal{D}(S) \times \mathcal{D}(S)$

$$\boxed{\Delta \text{ lift}(\mathcal{R}) \Theta} \quad \text{whenever}$$

- ▶ $\Delta = \sum_{i \in I} p_i \cdot s_i$, I a finite index set
- ▶ For each $i \in I$ there is a distribution Θ_i s.t. $s_i \mathcal{R} \Theta_i$
- ▶ $\Theta = \sum_{i \in I} p_i \cdot \Theta_i$
- ▶ $\sum_{i \in I} p_i = 1$

Many different formulations

Note: in decomposition $\sum_{i \in I} p_i \cdot s_i$ states s_i are not necessarily unique



Lifting actions: from $\boxed{s \xrightarrow{\mu} \Theta}$ to $\boxed{\Delta \xrightarrow{\mu} \Theta}$

$$\boxed{\Delta \xrightarrow{\mu} \Theta}$$

- ▶ Δ represents a cloud of possible process states
- ▶ each possible state must be able to perform μ
- ▶ all possible residuals combine to Θ

Examples:

- ▶ $(a.b + a.c)_{\frac{1}{2}} \oplus a.d \xrightarrow{a} b_{\frac{1}{2}} \oplus d$
- ▶ $(a.b + a.c)_{\frac{1}{2}} \oplus a.d \xrightarrow{a} (b_{\frac{1}{2}} \oplus c)_{\frac{1}{2}} \oplus d$
- ▶ $(a.b + a.c)_{\frac{1}{2}} \oplus a.d \xrightarrow{a} (b_p \oplus c)_{\frac{1}{2}} \oplus d$
- ▶ $(\tau.a + \tau.b)_{\frac{1}{2}} \oplus (\tau.a + \tau.c) \xrightarrow{\tau} a_{\frac{1}{2}} \oplus (b_{\frac{1}{2}} \oplus c)$



Bisimulations in an MLTS

$$\Delta \approx_{bis} \Theta$$

if, for each $\mu \in \text{Act}_{\tau, \delta} \cup \mathbb{R}^+$ and all finite sets of probabilities $\{p_i \mid i \in I\}$ satisfying $\sum_{i \in I} p_i = 1$,

- (i) whenever $\Delta \xrightarrow{\mu} \sum_{i \in I} p_i \cdot \Delta_i$, there is some $\Theta \xrightarrow{\mu} \sum_{i \in I} p_i \cdot \Theta_i$, such that $\Delta_i \approx_{bis} \Theta_i$ for each $i \in I$
- (ii) symmetrically, whenever $\Theta \xrightarrow{\mu} \sum_{i \in I} p_i \cdot \Theta_i$, there exists some $\Delta \xrightarrow{\mu} \sum_{i \in I} p_i \cdot \Delta_i$, such that $\Delta_i \approx_{bis} \Theta_i$ for each $i \in I$

Properties:

- ▶ \approx_{bis} is an equivalence relation
- ▶ $\Theta \xrightarrow{\tau} \Theta'$ such that $\Delta \text{ lift}(\approx_{bis}) \Theta'$



Simple bisimulations

$$\Delta \approx_{sbis} \Theta$$

if, for each $\mu \in \text{Act}_{\tau, \delta} \cup \mathbb{R}^+$,

- (i) whenever $s \xrightarrow{\mu} \Delta'$, there is some $\Theta \xrightarrow{\mu} \Theta'$, such that $\Delta' \text{ lift}(\approx_{sbis}) \Theta'$
- (ii) there exists some $\Delta \in \mathcal{D}(S)$ such that $\bar{s} \xrightarrow{\tau} \Delta$ and $\Theta \text{ lift}(\approx_{sbis}) \Delta$.

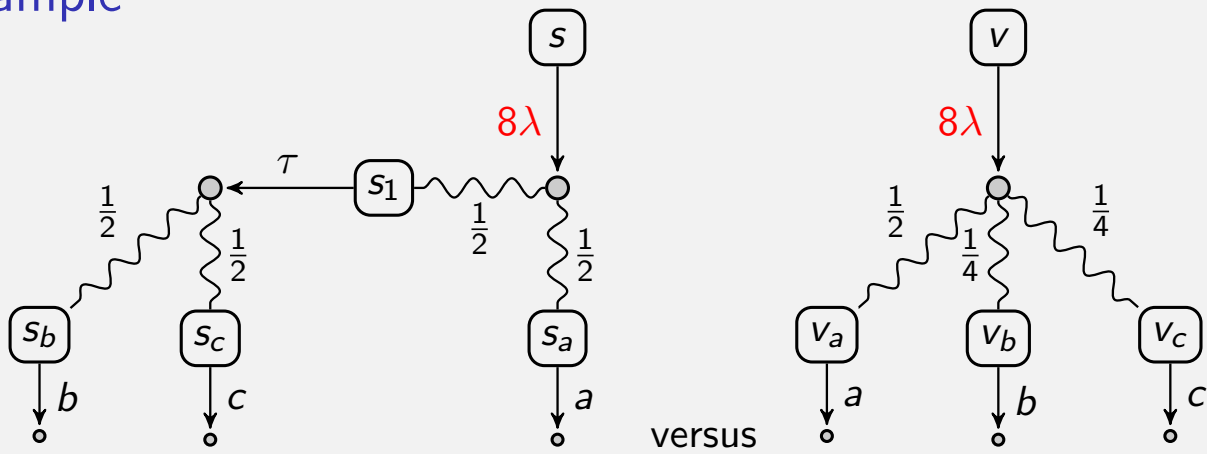
Theorem:

In a finitary MLTS

- ▶ $\Delta \text{ lift}(\approx_{sbis}) \Theta$ implies $\Delta \approx_{bis} \Theta$
- ▶ $\Delta \approx_{bis} \Theta$ implies $\Delta \text{ lift}(\approx_{sbis}) \Theta'$, where $\Theta \xrightarrow{\tau} \Theta'$



Example



Yes: $s \approx_{sbis} \bar{v}$ because of simple bisimulation

$$s \leftrightarrow \bar{v}$$

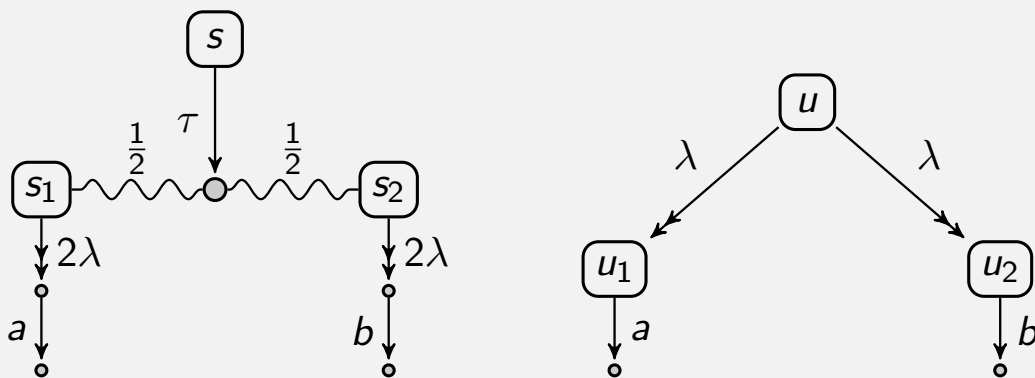
$$s_1 \leftrightarrow \frac{1}{2} \cdot \bar{v}_b + \frac{1}{2} \cdot \bar{v}_c$$

$$s_* \leftrightarrow \bar{v}_*$$

$$v \leftrightarrow \bar{s}$$

$$v_* \leftrightarrow \bar{s}_*$$

Example (MAs)



No: $s \not\approx_{sbis} \bar{u}$ because

$$s \xrightarrow{\tau} \frac{1}{2} \cdot \bar{s}_1 + \frac{1}{2} \cdot \bar{s}_2$$

can not be matched by \bar{u}

Markovian CCS

$$\begin{aligned}
 P, Q & ::= \mathbf{0} \mid \delta.P \mid \lambda.D, \lambda \in \mathbb{R}^+ \mid \mu:D, \mu \in \text{Act}_\tau \\
 & ::= \mid P + Q \mid P \mid Q \mid A \quad \text{declared definitions} \\
 D & ::= (\oplus_{i \in I} p_i \cdot P_i)
 \end{aligned}$$

Intensional semantics: an MA

- ▶ states: terms P, Q
- ▶ arrows: $P \xrightarrow{\mu} \Delta$ and $P \xrightarrow{\mathbf{d}} \Delta$ defined inductively



Rules for parallel

$$\begin{array}{c}
 \text{(PAR.L)} \\
 \frac{s \xrightarrow{\mu} \Delta}{s \mid t \xrightarrow{\mu} \Delta \mid \bar{t}}
 \end{array}
 \qquad
 \begin{array}{c}
 \text{(PAR.R)} \\
 \frac{t \xrightarrow{\mu} \Theta}{s \mid t \xrightarrow{\mu} \bar{s} \mid \Theta}
 \end{array}$$

$$\begin{array}{c}
 \text{(PAR.I)} \\
 \frac{s \xrightarrow{a} \Delta, t \xrightarrow{\bar{a}} \Theta}{s \mid t \xrightarrow{\tau} \Delta \mid \Theta}
 \end{array}$$

$$\begin{array}{c}
 \text{(PAR.L.T)} \\
 \frac{s \xrightarrow{\mathbf{d}} \Delta, t \xrightarrow{\delta} \Theta, s \mid t \not\xrightarrow{\tau}}{s \mid t \xrightarrow{\mathbf{d}} \Delta \mid \Theta}
 \end{array}
 \qquad
 \begin{array}{c}
 \text{(PAR.R.T)} \\
 \frac{s \xrightarrow{\delta} \Delta, t \xrightarrow{\mathbf{d}} \Theta, s \mid t \not\xrightarrow{\tau}}{s \mid t \xrightarrow{\mathbf{d}} \Delta \mid \Theta}
 \end{array}
 \quad \mathbf{d} = \delta, \lambda$$

$P \mid Q \xrightarrow{\mathbf{d}} \Delta$ only if

- ▶ **both** P and Q can delay
- ▶ at least one has to perform indefinite delay δ



Example: $Q = (\lambda_1.P_1 \mid \lambda_2.P_2)$

- ▶ $Q \xrightarrow{\lambda_1} (P_1 \mid \lambda_2.P_2)$ because of $\lambda_1.P_1 \xrightarrow{\lambda_1} P_1$ and $\lambda_2.P_2 \xrightarrow{\delta} \lambda_2.P_2$
- ▶ $Q \xrightarrow{\lambda_2} (\lambda_1.P_1 \mid P_2)$ because of $\lambda_1.P_1 \xrightarrow{\delta} \lambda_1.P_1$ and $\lambda_2.P_2 \xrightarrow{\lambda_2} P_2$
- ▶ $Q \xrightarrow{\delta} Q$ because of $\lambda_1.P_1 \xrightarrow{\delta} \lambda_1.P_1$ and $\lambda_2.P_2 \xrightarrow{\delta} \lambda_2.P_2$.

some **Other rules**

$$\text{(ACTION)} \\ \mu.D \xrightarrow{\mu} [D]$$

$$\text{(DELAY)} \\ \lambda.D \xrightarrow{\lambda} [D],$$

$$\text{(\delta.E)} \\ \frac{P \xrightarrow{\mu} \Delta}{\delta.P \xrightarrow{\mu} \Delta}$$

$$\text{(EXT)} \\ \frac{P \xrightarrow{\delta} \Delta_1, Q \xrightarrow{\delta} \Delta_2}{P + Q \xrightarrow{\delta} \Delta_1 + \Delta_2}$$

$$\text{(D.\delta)} \\ \lambda.D \xrightarrow{\delta} \overline{\lambda.D}$$

$$\text{(\delta.D)} \\ \frac{P \not\xrightarrow{\mu}}{\delta.P \xrightarrow{\delta} \overline{P}}$$

$$\text{(EXT.D.L)} \\ \frac{P \xrightarrow{\delta} \Delta, Q \not\xrightarrow{\delta}, Q \not\xrightarrow{\mu}}{P + Q \xrightarrow{\delta} \Delta}$$

External actions are **insistent**

- ▶ $(\lambda.Q \mid a:P)$ can not delay because
 - ▶ $a:P \not\stackrel{d}{\rightarrow}$

- ▶ $\lambda.Q \mid a.P \stackrel{\lambda}{\mapsto} Q \mid a.P$ because
 - ▶ $\lambda.Q \stackrel{\lambda}{\mapsto} Q$
 - ▶ $a.P \stackrel{\delta}{\mapsto} a.P$

Lazy $a.P$ is defined recursively by

$$a.P \Leftarrow a:P + \delta.a.P$$

Compositionality

Theorem:

In a finitary MA, $\Delta \approx_{bis} \Theta$ implies $\Delta \mid \Gamma \approx_{bis} \Theta \mid \Gamma$

A very general semantic equivalence

$P \approx_{rbc} Q$ is the largest relation which is

- ▶ compositional
 - ▶ preserved by some natural parallel operator on systems
- ▶ reduction-closed
 - ▶ preserved in some manner internal nondeterministic choices
- ▶ preserves barbs
 - ▶ some primitive observations

Has been defined for

- ▶ process calculi(CCS, CSP, ...), object languages, λ -calculus, higher-order processes, ...

In each case a variation on *bisimulations* have been justified as a proof methodology



Thesis

- ▶ A bisimulation equivalence provides a **proof method** for the natural semantic equivalence, \approx_{rbc}
- ▶ It is *sound* if $P \approx_{bis} Q$ implies $P \approx_{rbc} Q$
 - ▶ to prove a semantic identity it is sufficient to provide a witness bisimulation
- ▶ It is *complete* if $P \approx_{rbc} Q$ implies $P \approx_{bis} Q$
 - ▶ if a semantic identity is true it is possible to demonstrate it

Theorem:

In mCCS, our bisimulations are sound and complete



Barbs

$\Delta \Downarrow_a^{\geq p}$ whenever

- ▶ $\Delta \xrightarrow{\tau} \Delta'$
- ▶ probability of Δ' performing external action a is at least p .

\mathcal{R} is barb-preserving if whenever $\Delta \mathcal{R} \Theta$

- ▶ $\Delta \Downarrow_a^{\geq p}$ iff $\Theta \Downarrow_a^{\geq p}$

Reduction-closure

$\Delta \Longrightarrow \Delta'$

whenever Δ can evolve to Δ' via

- ▶ internal computations $\xrightarrow{\tau}$
- ▶ passage of time

\mathcal{R} is reduction-closed if whenever $\Delta \mathcal{R} \Theta$

- ▶ if $\Delta \Longrightarrow \Delta'$, there is a $\Theta \Longrightarrow \Theta'$ such that $\Delta' \mathcal{R} \Theta'$
- ▶ if $\Theta \Longrightarrow \Theta'$, there is a $\Delta \Longrightarrow \Delta'$ such that $\Delta' \mathcal{R} \Theta'$.

Future work

- ▶ A modal logic which characterises \approx_{bis} ?
- ▶ A polynomial-time algorithm for checking if $\Delta \approx_{bis} \Theta$?
- ▶ which returns a distinguishing formula if $\Delta \not\approx_{bis} \Theta$?
- ▶ Model-checking algorithms?
- ▶ Algebraic characterisation for finite terms in mCCS?
- ▶ Categorical justification for \approx_{bis} ?