Dynamic EM in Neologism Evolution

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Motivation

Models

Dynamic Model Static Model

EM Estimation

Experiments Data and Settings Results

Comparisons and Future Work

semantic neologism: when an old word acquires a new usage/meaning

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old sense: a construction process involving bricks, as in (from 2001) In 1611 she was **bricked** into one of the rooms



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old sense: a construction process involving bricks, as in (from 2001) ... In 1611 she was **bricked** into one of the rooms ...

recent sense: render a piece of equipment, often a phone, entirely unresponsive, as in (from 2011)

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I've tried to flash a custom ROM and now I think I've $\ensuremath{\textit{bricked}}$ my phone

Other examples

crawled some kind of movement vs. traversal of www by a web-crawler *tweet* high-pitched bird noise vs. post to Twitter web-site

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can make problems for SMT when its training data pre-dates the neologism's emergence

some translations into German via Google Translate¹:

| English | German (via Google Translate) |
|-------------------------|--------------------------------------|
| he is a regular tweeter | er ist ein regelmaessiger Hochtoener |
| he has bricked my phone | er hat mein Handy zugemauert |

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The question is:

Can semantic neologisms be detected from untagged text?

¹Executed May 2013.

Representation and Notation

To talk about an occurrence of an ambiguous word will use:

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- W: words to left and right of a target
- W_i : *i*-th word in **W**
- Y: year of occurrence
- S: sense of target occurrence of targets

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Eg. samples of bricked:

2001: ... In 1611 she was **bricked** into one of the rooms ... 2011: I've tried to flash a custom ROM and now I think I've **bricked** my phone

become instances:

 $Y = 2001, S = 1, W = \langle L, In, 1611, she, was, into, one, of, the, rooms \rangle$ $Y = 2011, S = 2, W = \langle and, now, I, think, I've, my, phone, R, R, R \rangle$

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Time dependent Sense Model

Without loss of generality, using the chain rule, we have

 $p(Y, S, \mathbf{W}) = p(Y) \times p(S|Y) \times p(\mathbf{W}|S, Y)$

The p(S|Y) term directly expresses the idea that the prevalence of a sense can vary with the year

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If we now assume that $p(\mathbf{W}|S, Y) = p(\mathbf{W}|S)$ ie. W is conditionally independent of Y given S we get first line below

Definition (Dynamic Sense Model)

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(1)

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$$= p(Y) \times p(S|Y) \times \prod_{i} p(W_{i}|S)$$
(2)

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Second line above by treating W as 'bag of words'

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If we further assume that p(S|Y) = p(S) we get:

Definition (Static Sense Model)

 $p(Y, S, \mathbf{W}) = p(Y) \times p(S) \times p(\mathbf{W}|S)$

Let θ be all parameters: p(Y), p(S|Y), p(W|S).

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Data has no sense annotation.

Let θ be all parameters: p(Y), p(S|Y), p(W|S).

Data has no $\underline{\mathsf{sense}}$ annotation. So use EM to make converging sequence of estimates

 $\theta_0 \to \ldots \to \theta_n \to \theta_{n+1} \to \ldots \to \theta_{\text{final}}$

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(E) generate a virtual corpus of disambiguated instances by treating each training instance (Y^d, \mathbf{W}^d) as standing for all possible completions with a sense, (Y^d, S, \mathbf{W}^d) , weighting each by its conditional probability $P(S|Y^d, \mathbf{W}^d; \theta_n)$, under current probabilities θ_n

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- (M) apply maximum likelihood estimation to the virtual corpus to derive new estimates θ_{n+1} .

EM update equations

For each data item d, let $\gamma_{\theta_n}^d(s)$ be the conditional S-prob under θ_n ie.

$$\gamma^d_{\theta_n}(s) := P(S = s | Y = y^d, \mathbf{W} = \mathbf{w}^d; \theta_n)$$

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can prove the E-M cycle leads to update formulae:

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can prove the E-M cycle leads to update formulae:

$$P(S = s | Y = y; \theta_{n+1}) = \frac{\sum_{d} (\text{if } Y^{d} = y \text{ then } \gamma_{\theta_{n}}^{d}(s) \text{ else } 0)}{\sum_{d} (\text{if } Y^{d} = y \text{ then } 1 \text{ else } 0)}$$

$$P(w|S = s; \theta_{n+1}) = \frac{\sum_{d} (\gamma_{\theta_{n}}^{d}(s) \times freq(w \in \mathbf{W}^{d}))}{\sum_{d} (\gamma_{\theta_{n}}^{d}(s) \times length(\mathbf{W}^{d}))}$$

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- to get time-specific samples used the Google facility to specify a time period for searched documents
 eg. search: "bricked" 1/1/2000 – 31/12/2000
- saved 100 per year
- used window 5 words to the left of the target, and 5 words to the right

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- ▶ per-sense word probs initialised to overall corpus probs + some noise
- sense distribs initialised $\frac{7}{20}$, $\frac{11}{20}$, $\frac{2}{20}$

Outline

Motivation

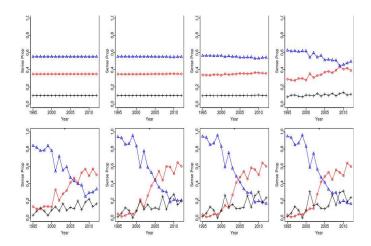
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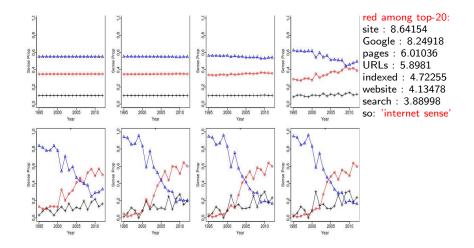
Comparisons and Future Work

EM converging to solution for 'crawled'



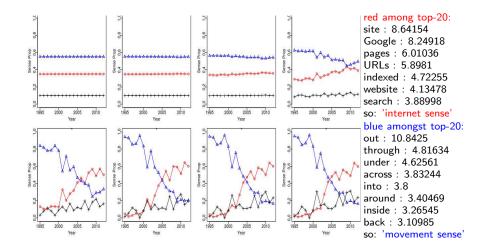
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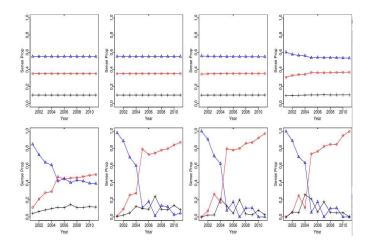


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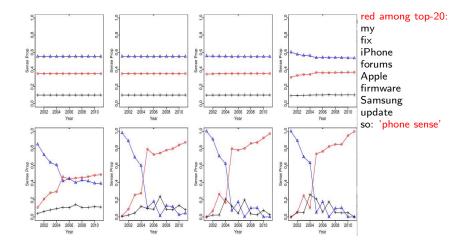


EM converging to solution for 'bricked'



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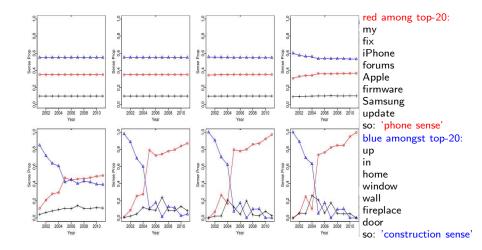
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Comparing to labelled target

the algorithm learns from data with no sense data. For 'bricked' we hand-labelled to give a target to compare to.

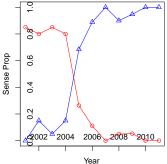
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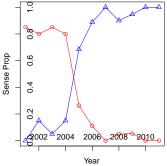
▶ The inferred sense distrib resembles the empirical target:



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 If the EM-trained models are used to label the data, then dynamic model accuracy: 82.4%.
 static model accuracy: 76.1%

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Conclusions and Further Directions

- some evidence that can spot a semantic neologism
- further data
- more elaborate models: prior on year-to-year change

comparison to LDA and dynamic topic models