Lockless Algorithms

- CAS based algorithms
- stack
- order linked list
- memory management (hazard pointers)

Obstruction, Lock and Wait Free Methods

- obstruction free method guaranteed to complete in some bounded number of program steps if no other thread executes any steps during that same interval [easiest]
- lock free a method M is said to be lock free if some thread is guaranteed to make progress in some bounded number of M's program steps
- wait free if method M is guaranteed to complete in some bounded number of its own program steps - bound need not be statically known [hardest]

Obstruction, Lock and Wait Free Methods...

- a lock based solution is not obstruction free, if a thread sleeps holding the lock then NO other thread cannot make progress
- solutions based on CAS or LL/SC are normally lock free; the only way to prevent CAS succeeding is if some other CAS succeeds meaning that some other thread is making progress; solution may NOT be wait free as a particular thread's CAS may never succeed
- wait free solutions often based on helper functions, if a thread finds itself "blocked" by another thread, it completes the action on behalf of the other thread first [unblocks the blockage!]; implementations often idempotent as many threads may try to perform the same action which must only be effectively executed once.
- linearization point instruction where method takes effect [eg. marking a node when removing node from concurrent CAS based ordered linked list]

Lockless Stack

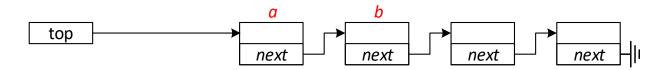
```
Node *top = NULL; // top of stack
void push(Node *n) {
    do {
        Node *o = top; // copy pointer
        n->next = o;
    } while (CAS(&top, o, n) == 0);
}
```

```
Node* pop() {
    Node *o, *n;
    do {
        o = top; // copy pointer
        if (o == NULL)
            return NULL;
        n = o->next;
    } while (CAS(&top, o, n) == 0);
    return o;
}
```

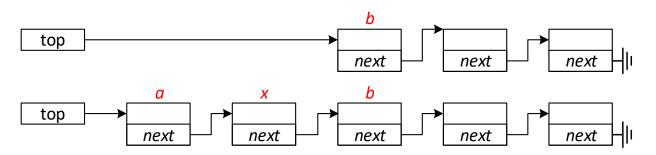
- CAS returns 1 if successful
- threads can push and pop nodes "concurrently"
- what can possibly go wrong? algorithm suffers from the ABA problem

Lockless Stack

• imagine the following stack and execution interleave...



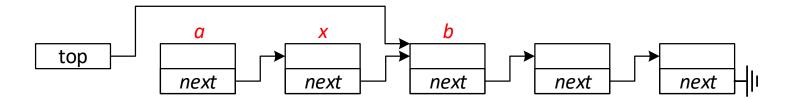
- thread 0 executes pop(), but gets <u>pre-empted</u> after executing n = o->next [n = b]
- thread 1 now pops node *a* from stack and <u>then</u> pushes nodes *x* and *a*, **REUSING** node *a*



• thread 0 is then rescheduled and executes its CAS which will succeed!

Lockless Stack

• CAS succeeds, BUT stack is left in the following state



- node *a* returned, but "two nodes popped from stack"
- called the ABA problem because top is assigned A, then B and then A again
 - the different A is not detected
- the Trieber [1986] stack uses a sequence count embedded in the top-of-stack pointer to avoid the ABA problem [counted pointer]
- needs a double length CAS DCAS [IA32 cmpxchg8b, x64 cmpxchg16b]

cmpxchg8b (IA32) / cmpxchg16b (x64)

Operation

```
IF (64-Bit Mode and OperandSize = 64)
  THEN
     TEMP128 ← DEST
     IF (RDX:RAX = TEMP128)
       THEN
          ZF \leftarrow 1;
          DEST \leftarrow RCX:RBX;
        FLSE
          ZF \leftarrow 0:
          RDX:RAX \leftarrow TEMP128;
          DEST \leftarrow TEMP128;
          FI;
     FI
  ELSE
     TEMP64 \leftarrow DEST;
     IF (EDX:EAX = TEMP64)
        THEN
          ZF \leftarrow 1;
          DEST \leftarrow ECX:EBX;
       ELSE
          ZF \leftarrow 0;
          EDX:EAX \leftarrow TEMP64;
          DEST \leftarrow TEMP64;
          FI;
     FI;
FI;
```

DCAS(a, e, n)

a typically in a register rsi or rdi rdx:rax = e rcx:rbx = n

DCAS(a, e, n)

a typically in a register esi or edi edx:eax = e ecx:ebx = n

Trieber Lockless Stack

```
<Node*, int> top; // Node* and count

void push(Node *n) {

    do {

        <o, c> = top; // take atomic copy

        n->next = o;

    } while (CAS(&top, o, n) == 0);

}
```

```
Node* pop() {
    do {
        <o, c> = top; // take atomic copy
        if (o == NULL)
            return NULL;
        n = o->next;
    } while (DCAS(&top, <o, c>, <n, c+1>) == 0);
    return o;
```

- pseudo C/C++
- count incremented each time a node popped from stack
- count wrap around is potentially a problem
- DCAS not necessary in push, CAS used instead
- original push code works with an ABA sequence it doesn't matter if the first Node has changed as always pushing on to front of stack

Trieber Lockless Stack...

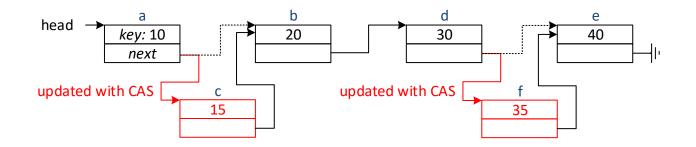
- lockless, but not much concurrency as access to top is a serious bottleneck
- is algorithm obstruction, lock or wait free?
- lock free since a thread could be in an endless loop trying to push a Node on to stack, BUT for its CAS to fail another thread must be making progress
- ABA problem will not occur if algorithm implemented using LL/SC why? overwrite of top always detected
- alternatively, don't reuse node until threads don't have and cannot get a pointer to the node [discussed later in lockless ordered list implementation]

Lockless List

- ordered linked list or set
 - add(key)
 - remove(key)
- support concurrent *add(key)* and *remove(key)* operations
- would like number of operations per second to increase linearly with the number of threads
- need to consider memory management
 - if memory allocation / dealloction [new, delete, malloc and free] NOT lockless it could be a bottleneck
- can be hard to reason about an algorithm that works on a list which is concurrently being modified by other threads
- quite a challenge

Using CAS to add nodes

• use CAS to add nodes 15 and 35



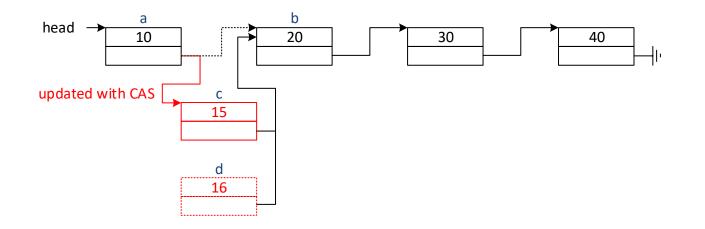
• search for insertion point, initialise next pointer and then execute CAS with correct parameters to insert node into list

CAS(&a->next, b, c); // add node c between a and b CAS(&d->next, e, f); // add node f between d and e

• disjoint-access parallelism

Using CAS to add nodes...

• if 2 threads try to add nodes at the same position

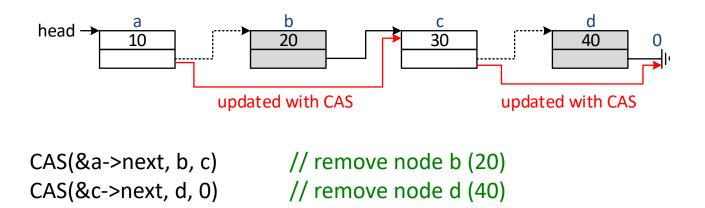


CAS(&a->next, b, c)// first CAS executed will succeed...CAS(&a->next, b, d)// and consequently second CAS executed will FAIL

- first CAS executed succeeds, second will fail as *a->next* != b
- <u>RETRY on failure</u>, which means searching for insertion point AGAIN [costly if list long] and, if key not found, set up and re-execute CAS

Using CAS to remove nodes

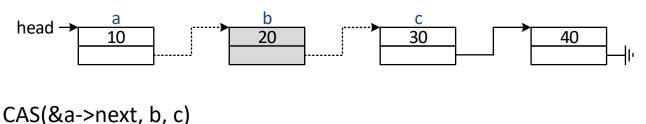
- search for node and then execute CAS with correct parameters to remove node from list
- consider 2 threads removing non-adjacent nodes



• disjoint access parallelism

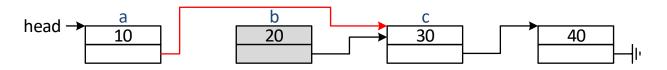
Using CAS to remove nodes...

• if two threads try to remove the same node



CAS(&a->next, b, c)

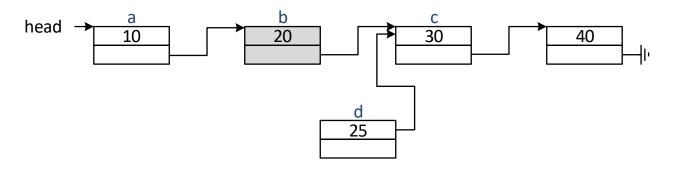
• first CAS executed succeeds



- second CAS executed fails as *a->next != b*
- <u>RETRY on failure</u>, which means searching AGAIN for node [which may not be found]

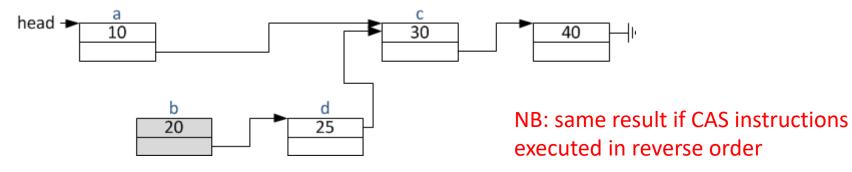
What can go wrong with remove?

imagine removing node 20 and adding node 25 concurrently •



CAS(&a->next, b, c); // remove 20 CAS(&b->next, c, d);

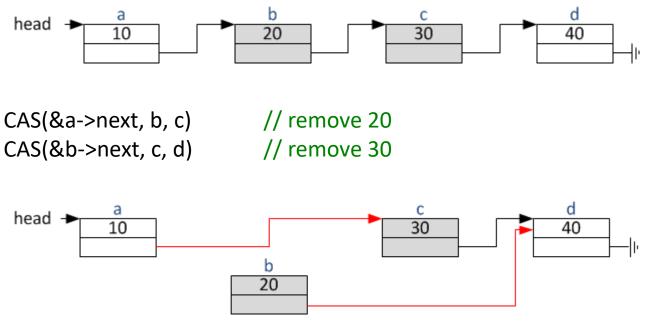
// add 25



NOT what was intended! ٠

What else can go wrong with remove?

• consider deleting adjacent nodes

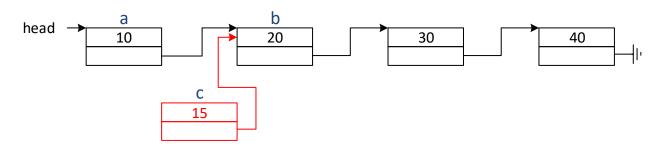


• AGAIN NOT what was intended

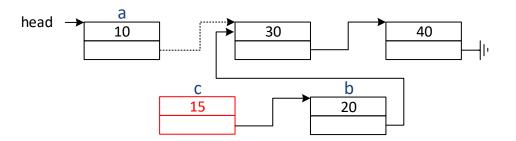
NB: similar result if CAS instructions executed in reverse order (nodes 20 and 30 swapped)

ABA Problem Again

 imagine <u>insertion</u> point found, BUT before CAS(&a->next, b, c) is executed, thread is preempted



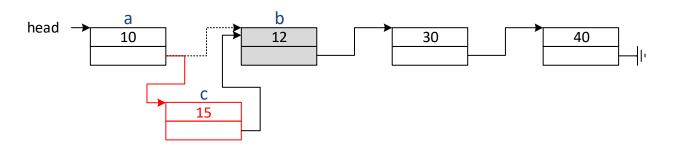
• another thread <u>then</u> removes b from list



- if thread adding 15 resumes execution, the CAS fails which is OK in this case
- BUT need to consider an alternative interleave where node b is reused

ABA Problem Again...

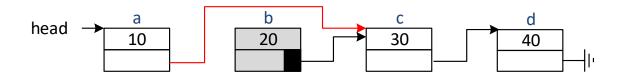
 if the <u>memory</u> used by b is reused, for example by a thread adding key 12 to the list before thread adding 15 resumes...



- when the thread adding 15 to list resumes, its CAS will succeed and 15 will be added into the list at the wrong position
- this is the ABA problem again
- nodes cannot be reused if any thread has or can get a pointer to the node

Lockless List

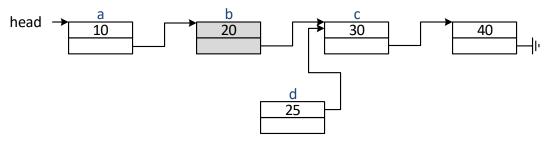
- used ideas from <u>A Pragmatic Implementation of Non-Blocking Linked Lists</u>, Tim Harris [2001], but code from...
- <u>Hazard Pointers: Safe Memory Reclamation for Lock-Free Objects</u>, Maged M. Michael [2004] [see Figure 9 in paper]
- initially ignore the ABA problem by not reusing nodes [will quickly run out of memory]
- two step removal eg. remove(20)



- (1) atomically mark node by setting LSB of next pointer [logically removes node]
- (2) remove node by updating next pointer using CAS
- avoids problem shown in slides <u>11</u> and <u>12</u> by detecting attempts to update the next field of a removed node

Revisit adding node [25] and removing node [20]?

• imagine adding node [25] and removing node [20] concurrently



(1) CAS(&b->next, c, d);

// add 25

<u>and</u>

- (3) CAS(&a->next, b, c); // remove b [20]
- if (1) executed first, (2) will fail as b->next != c
- if (2) executed first, (1) will fail as b->next != c
- if (3) fails, it means that a no longer points to b, BUT b is logically marked and can be removed later [OK for list to temporarily contain MARKED nodes]

Lockless List...

Fig 9. from <u>Hazard Pointers: Safe Memory Reclamation for Lock-Free Objects</u>, Maged M. Michael [2004]

structure NodeType { Key:KeyType; Next:*NodeType;};	Find(head:**NodeType;key:KeyType) : Boolean {
// Per-thread private variables	try_again:
prev: **NodeType; cur,next: *NodeType;	10: $prev \leftarrow head;$
//hp0 and hp1 are private ptrs to 2 of the thread's hazard ptrs.	11: $cur \leftarrow *prev;$
// Integer arithmetic in lines 6, 17, and 19.	12: while $(cur \neq null)$ {
	13: $*hp0 \leftarrow cur;$
Insert(head:**NodeType,node:*NodeType):Boolean {	14: if (*prev \neq cur) goto try_again;
1: key \leftarrow node: Key;	15: $next \leftarrow cur?Next;$
while true {	16: if (next & 1) { // bitwise AND
2: if Find(head,key) return false;	 if ¬CAS(prev,cur,next-1) goto try_again;
3: $node$.Next $\leftarrow cur$;	18: RetireNode(cur);
4: if CAS(prev,cur,node) return true;	19: $cur \leftarrow next-1$;
}	} else {
}	20: $ckey \leftarrow cur$. Key;
	21: if (*prev \neq cur) goto try_again;
Delete(head:**NodeType,key:KeyType):Boolean {	22: if $(ckey \ge key)$ return $(ckey = key)$;
while true {	23: $prev \leftarrow \&cur^Next;$
5: if ¬Find(head,key) return false;	24: $tmp \leftarrow hp0; hp0 \leftarrow hp1; hp1 \leftarrow tmp; // all private$
6: if ¬CAS(&cur [^] Next,next,next+1) continue;	25: $cur \leftarrow next;$
7: if CAS(prev.cur,next) RetireNode(cur); clsc Find(head.kcy);	}
8: return true:	}
1	26: return false;
	}
Search(head:**NodeType,key:KeyType):Boolean {	
9: return Find(head,key);	
}	

Lockless List...

- Node class
 - int key
 - Node *next
- List implemented using global variable *head* and functions *add, remove and find*
 - Node *head
 - int add(Node **head, Node*node)
 - int remove(Node **head, int key)
 - int find(Node **head, int key)
- per thread local variables
 - prev **Node
 - Node *cur
 - Node *next

// head of list
// insert node
// remove node with key
// find with key

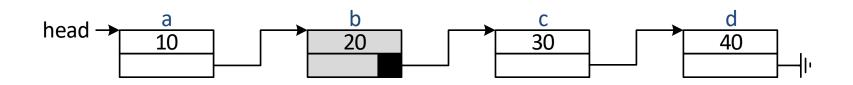
Lockless List...

- MARKED node indicated by an ODD address in its next field
- OK as addresses normally aligned on at least a 4 byte boundary [2 or 3 LSBs normally 0]
- handle marked nodes as follows

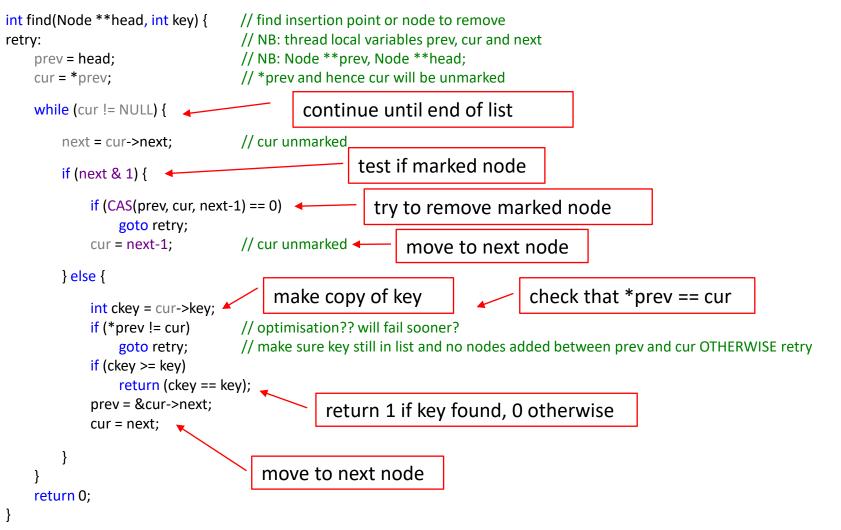
if (n->next & 1) ...// tests if node n MARKEDCAS(&n->next, v, v+1)// MARK node n (assumes node NOT MARKED)CAS(&n->next, v, v-1);// UNMARK node n (assumes node MARKED)

• <u>to atomically</u> mark node b [logically remove] use

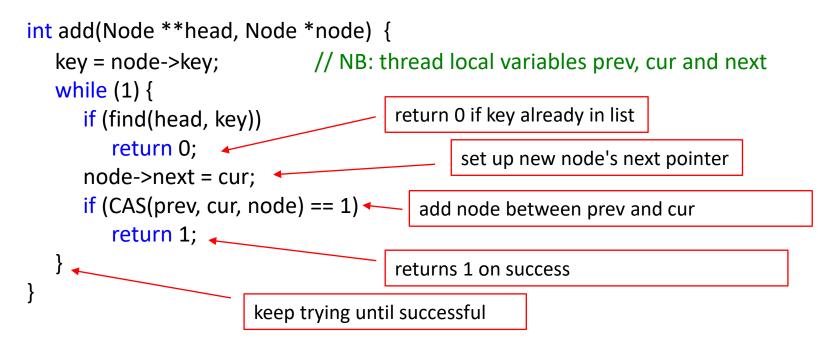
CAS(&b->next, c, c + 1); // assumes node UNMARKED



find()

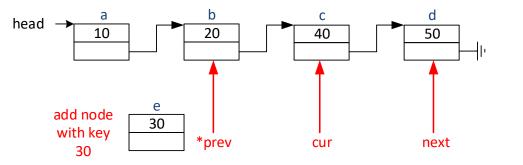


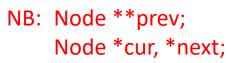
add()



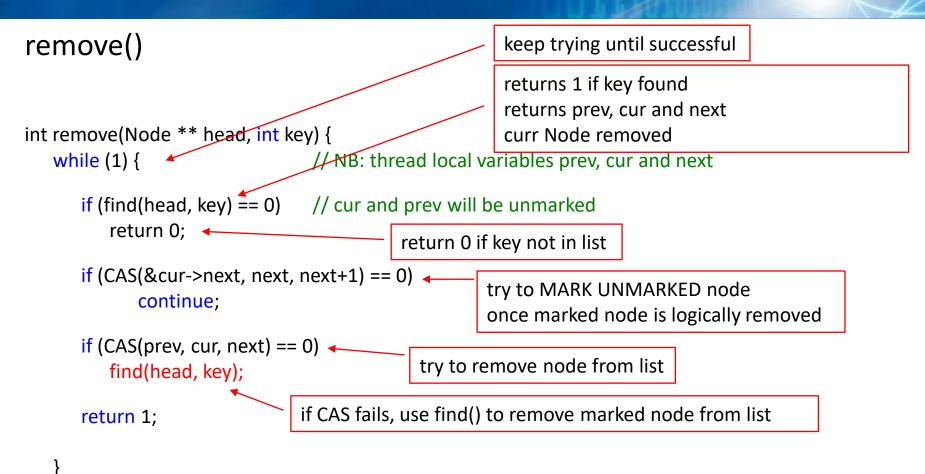
add() ...

• add(key) calls the find() function





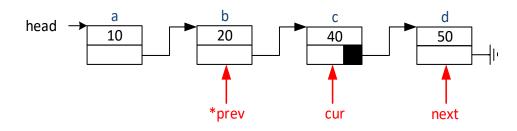
- find() returns thread local pointers such that the new node should be added between *prev and cur
- if CAS(prev, cur, node) succeeds, it must mean that prev still pointed to cur [nodes have not been added between prev and cur]
- a node CANNOT be added by linking to a MARKED node [logically removed] thus avoiding the problem discussed in slides <u>12</u> and <u>13</u>



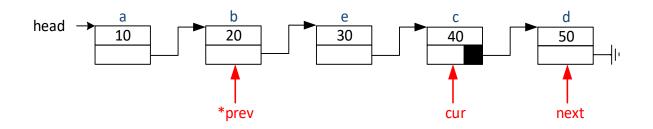
• calls find to remove marked node if CAS fails AND if find fails to remove the marked node, it can be removed by future calls to find (in add and remove)

remove() ...

 assume initial search has returned *prev, cur and next <u>AND</u> cur has been MARKED [logically removed]



 imagine that before CAS(prev, cur, next) is executed to remove node, another thread inserted a node between prev and cur



• CAS(prev, cur, next) will FAIL

remove() ...

- since node is logically removed, there is NO requirement to ensure that the node is removed from the linked list immediately
- BUT by calling find() again, any MARKED node(s) up to and including key will be removed
- NOT calling find() here, simply means that the MARKED node will remain in list until
 - a node is inserted after key

OR

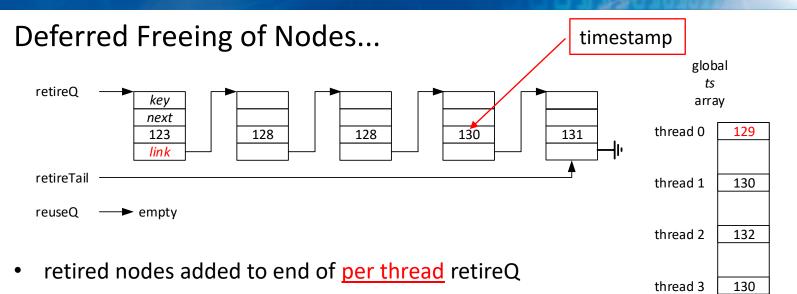
a node after or including key is removed

What still needs to be done?

- current solution avoids the ABA problem by NOT re-using nodes
- there is no code for freeing or reusing nodes
- ONLY a partial solution without memory management
 - garbage collection [supported by Java, but not yet by C++]
 - reference counting [perhaps by using smart pointers, reported to be slow]
 - method proposed by Harris [section 6 of paper]
 - hazard pointers [Michael]

Deferred Freeing of Nodes [Harris]

- see end of section 6 in Harris paper
- each node has an additional (1) *link* so that node can be added to a <u>per thread</u> retireQ or reuseQ and (2) a timestamp
- before starting an add or remove operation, each thread obtains a global timestamp and saves it in a global *ts* array indexed by the thread number [best if each timestamp is stored in its own cache line]
- can use clock() or the ___rdtsc() intrinsic or ... to obtain timestamp
- a remove operation retires the node by adding it to a per thread retireQ and sets the node's timestamp by reading its global timestamp
- when a thread needs a node and the reuseQ is empty, it can traverse the *retireQ* and transfer nodes to the reuseQ if their *timestamp* is less than the minimum *ts* of any thread because this means that NO thread can still have a reference to the node
- allows nodes to be recycled



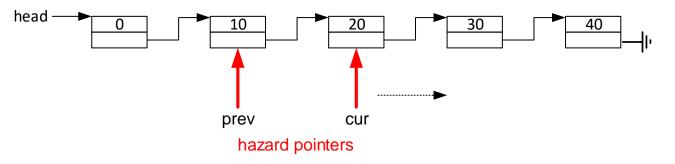
- if thread needs a node and reuseQ empty, try to transfer nodes from retireQ to reuseQ
- in example, minimum thread *ts* is 129
- can transfer all nodes in retireQ with *ts* < 129 to per thread reuseQ [first three nodes]
- allocate nodes from reuseQ and ONLY call new if reuseQ empty
- why is a *link* needed? why not use *next*?
 - thread may need to follow next in order to traverse node even when on retireQ

Deferred Freeing of Nodes...

- memory management algorithm is <u>NOT</u> obstruction free
- if a thread pre-empted, its global *timestamp* will NOT change [*stuck*]
- per thread *timestamp* also *stuck* if thread never calls add() or remove()!
 - if thread not running for 20ms, then 20ms worth of removed nodes will be added to the retireQs before they can be transferred to the reuseQs
 - can result in many allocated nodes, especially when threads > CPUs
- also need to make sure algorithm works when some threads are producers and others are consumers
 - nodes added to consumer reuseQs needed by producers
 - need to <u>free</u> nodes on reuseQ so nodes can be reused by producers
 - nodes recirculated
- implementation simplified by using per thread Qs

Hazard Pointers

- Hazard Pointers: Safe Memory Reclamation for Lock-Free Objects
- with an ordered linked list, two active pointers are used to traverse the list during a find operation [number of active pointers depends on algorithm]
- corresponds to the prev and cur pointers



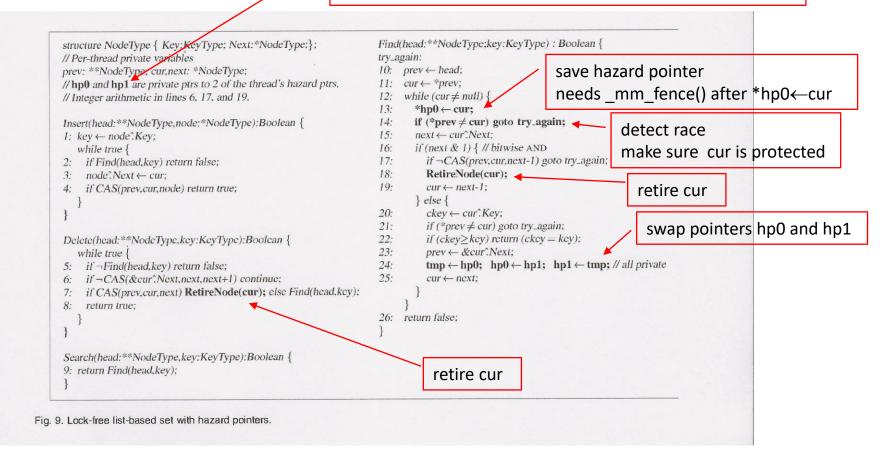
- at each step, copy prev and cur into an array of <u>per thread</u> hazard pointers
- idea is not to reuse or free nodes if they have hazard pointers pointing to them
- once a node has been removed from list, no thread is able to get a pointer to the node unless it has a pointer to it already

Hazard Pointers...

- maintain a global array of <u>per thread hazard pointers</u> [best if each thread saves its hazard pointers in its own cache line(s)]
- use a per thread retireQ and reuseQ as in previous example
- a thread retires a node by adding it to its retireQ
- when the length of its retireQ is >= 2*nthreads*HAZARDSPERTHREAD
 - take a local snapshot of ALL hazard pointers and store in a local array
 - optionally sort hazard pointers [in local array]
 - for each node on its retireQ, <u>if</u> address of node doesn't match any of the hazard pointers in the local array <u>then</u> transfer to reuseQ [at least half of the nodes should be transferred]
 - allows nodes to be recycled
- only need to call new if per thread reuseQ is empty
- can delete nodes instead of placing them on reuseQ

Lockless List...

hp0, hp1 are pointers to the locations where the two hazard pointers are stored [*hp0 = *hp1 = 0]



hazard pointers used to protect prev and cur

Lockless List...

- detect race make sure cur is protected
- between cur being assigned [cur = ...] and protected by hazard pointer [*hp0 = cur], cur could be moved to the retireQ or reuseQ, reused or even freed
- most straightforward way to make sure cur is protected by hazard pointer is to check that it is still in the list [*prev == cur]
- if cur is reused between cur = ... and *hp0 = cur <u>AND</u> *prev == cur, it is of NO consequence because at this particular point in the algorithm a comparison has not been made with cur->key
- if cur is freed between cur = ... and *hp0 = cur, accessing the node pointed to by cur could be result in a invalid memory access
- the _mm_fence() is to make sure that the hazard pointer is visible to ALL other threads thus protecting cur

Baseline Performance Single Threaded Ordered List

C:\V	Vindows\system	n32\cmd	l.exe								. O <mark>X</mark>
LOCKT	YP=0 ALIGNE	ED NOF 6 mode 4 K 8 4 K 8 4 K 8	P=1000 M 1 94 st 3 N 64 3 N 64 3 N 64 4 N 1024	NSECONDS=2 Lepping 3 4 4 4	bit) 64 bit ex PREFILL USETS Intel(R) Xeon(XALLOC size	of(Node)=10	5	AM=64GB 27-No	v-2015 09:04:	24
	maxKey	nt	pft	rt	ops	ops/s	vmUse	memUse			
	16 64 256 1024 4096 16384 65536 262144 1048576		$\begin{array}{c} & & & \\ 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \\ 0.01 \end{array}$	2.00 2.00 2.00 2.00 2.00 2.00 2.02 2.00 2.15 3.22	5000 51335000 51392000 5193920000 5193920000 5193920000 5193920000 51939200000000000000000000000000000000000	40647176 24329335 9691154 2208395 242015 33730 12468 3258 621	2.42MB 2.42MB 2.42MB 2.42MB 2.42MB 2.42MB 2.42MB 4.42MB 10.43MB 34.48MB	3.76MB 3.77MB 3.77MB 3.80MB 3.89MB 4.27MB 5.77MB 11.78MB 35.83MB			
16/1/ 64/1/ 256/1 1024/ 4096/ 16384 65536 26214	y, nt, rt, 2001/81335(2001/486830 /2001/1939] 1/2001/4419 /1/2004/4850 /1/2016/680 /1/2016/680 /1/2005/25(4/1/2148/77 76/1/3217/20	000 000 2000 9000 000 000 000 000	per thre	ead							
Press	key to qu	it			III						

- ALIGNED: each node in its own cache line
- PREFILL: list prefilled with odd integers for quick start up
- 50% add random key and 50% remove random key
- decreasing ops/s as list length increases [average list length maxKey/2]

Lockless list with Hazard Pointers

node needs a link field as it can effectively be in list and on retireQ simultaneously

$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	256K L 6 8192K L 6	4 K 4 K 4 K 1	4 N 1024	4				rela	ative sp	peed up			
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- good speed up with # threads [max speed up 7.63]
- BUT algorithm slow compared with baseline [64K 1 thread 12,468 : 3,894]
- 64K baseline 12,468, lockless 8 threads 23,706 [almost twice as fast]

Preview - lockless list using transactional memory (TSX)

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- good speed up with # threads [max speed up 5.22]
- algorithm almost as quick as baseline [64K 1 thread 12,468 : 14,324]
- 64K baseline 12,468, lockless 8 threads 62,810 [almost 5x faster]

Learning Outcomes

- you are now able to:
 - explain the difference between obstruction, lock and wait free algorithms
 - explain the operation of the Compare and Swap (CAS) instruction
 - implement a lockless stack using CAS
 - explain the ABA problem and some possible solutions
 - implement a lockless ordered list using CAS
 - assess the difficulty of adding memory management to a CAS based concurrent algorithm
 - add memory management to a lockless algorithm using hazard pointers