DbC for multiparty distributed interactions: static & dynamic validation

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BACKGROUND

- DbC: Assertions = Types + Logical Formulae
- Type signature

```
int foobar(int i)
```

Assertion

```
int foobar(int i) {
    pre: {i>10}
    post: {0 < result < 1000}
}</pre>
```

- Building systems on the basis of precise contracts
 - restrain defensive programming
 - provide robustness

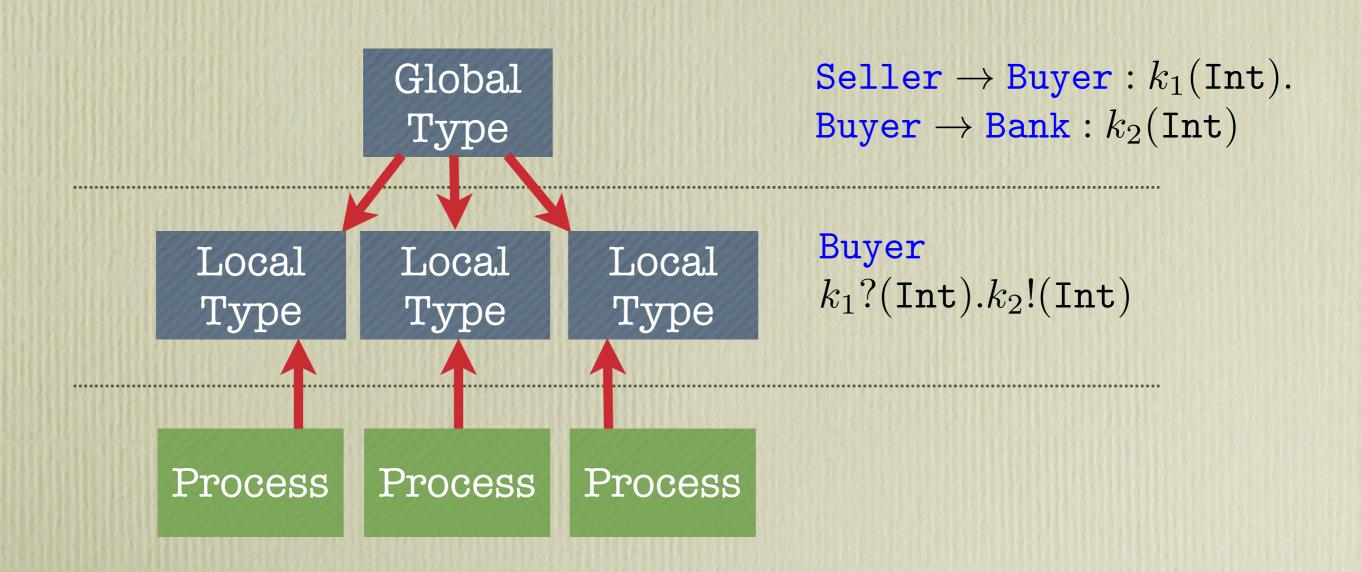


CHALLENGES

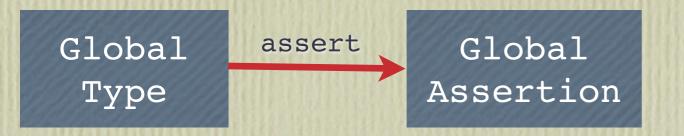
Can we extend this framework to communications and concurrency?

- Distributed Setting (asynchronous message passing)
- The responsibilities are spread among the participants
- Participants have **different views** of the contract, e.g., the condition of an interaction is
 - a post-condition for the sender
 - a pre-condition for the receiver
 - what about third parties?

Multiparty Session Types



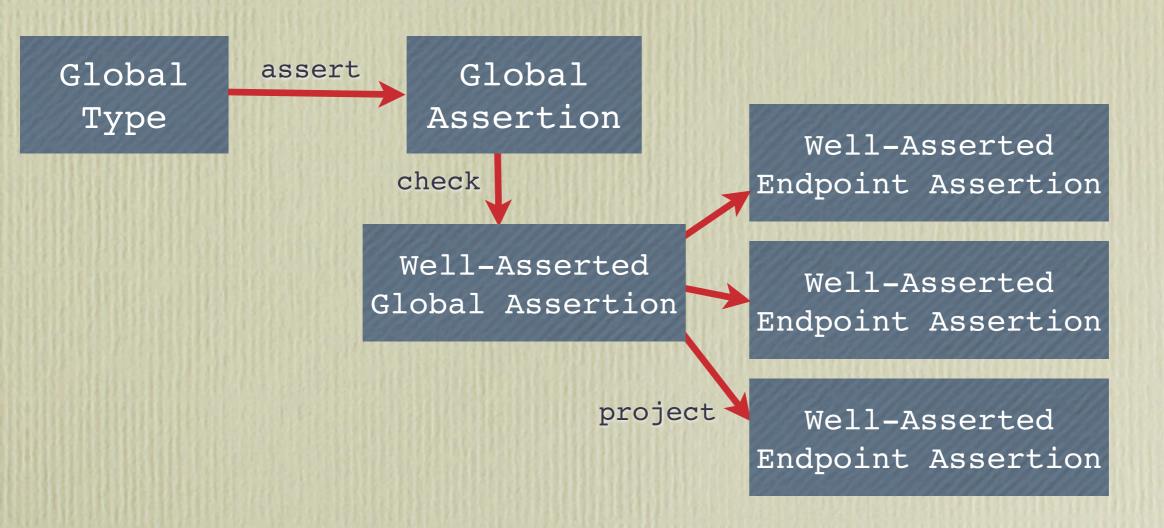




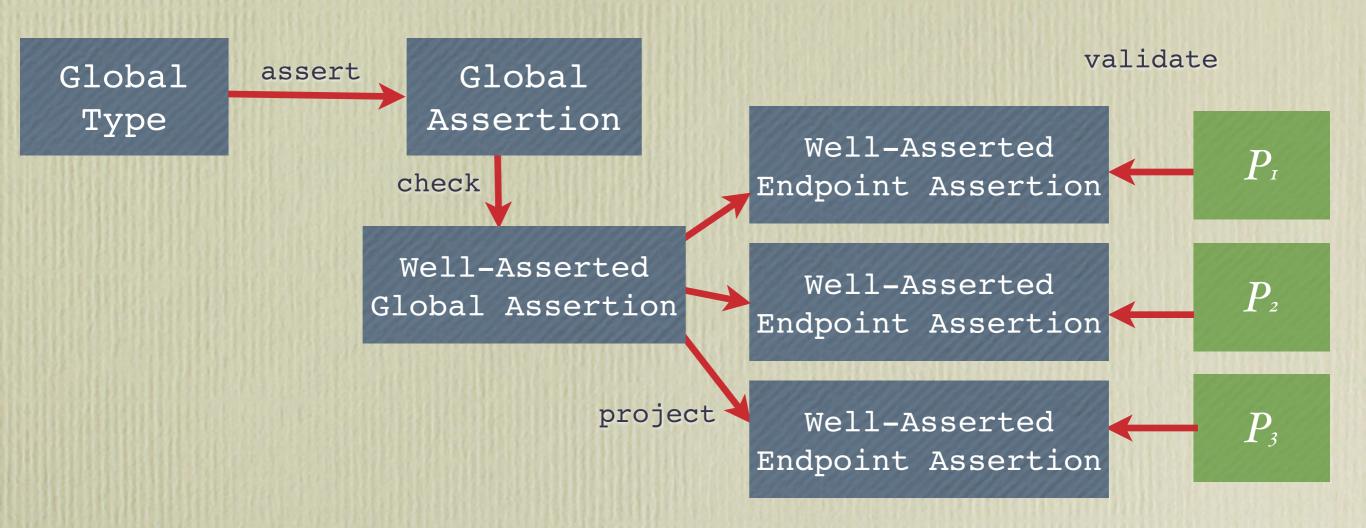
- A **global type** is used as a type signature describing the interactions of a multiparty **session**
- Each abstract action is annotated with a predicate



• Consistency of the global specification is checked

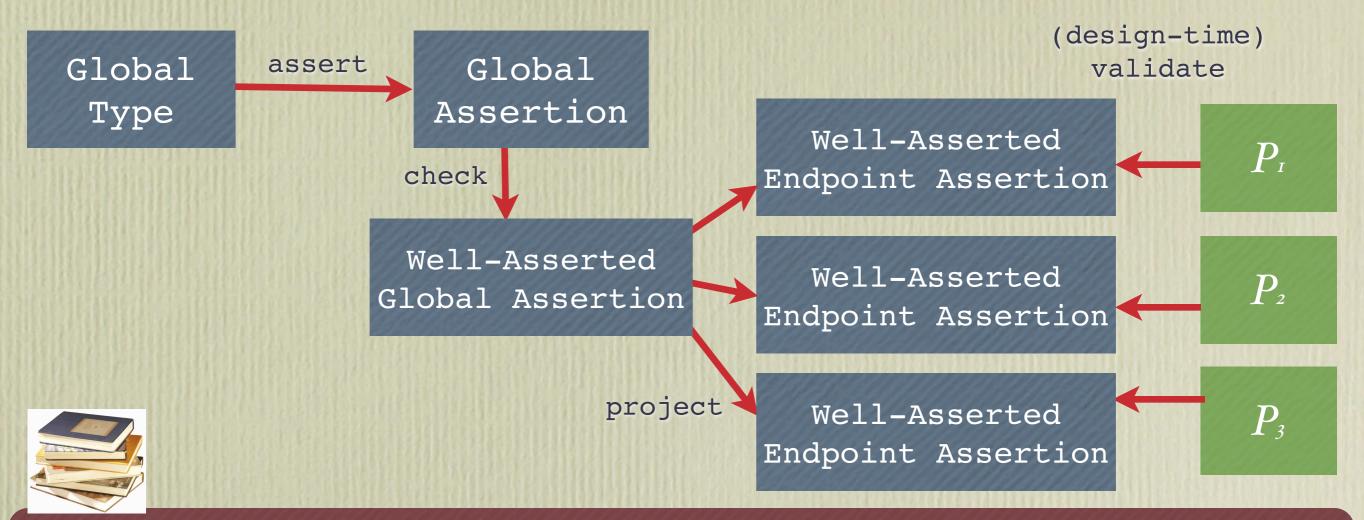


• The global assertion is **projected** onto each endpoint **preserving consistency**



• Each process is **validated** against its (one or more) local specification(s)

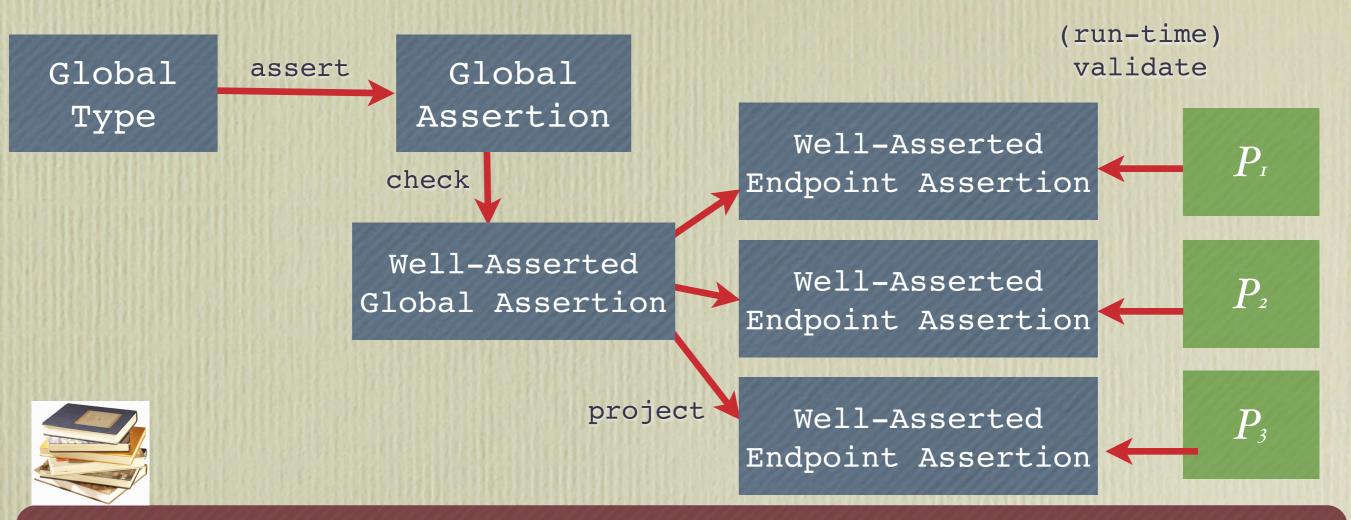
STATIC VALIDATION



Laura Bocchi, Kohei Honda, Emilio Tuosto, and Nobuko Yoshida **A Theory of DbC for Multiparty Distributed Interactions** (CONCUR 2010)

- Key points: effective well-assertedness, projection, validation*
- The proof system is sound and relatively complete

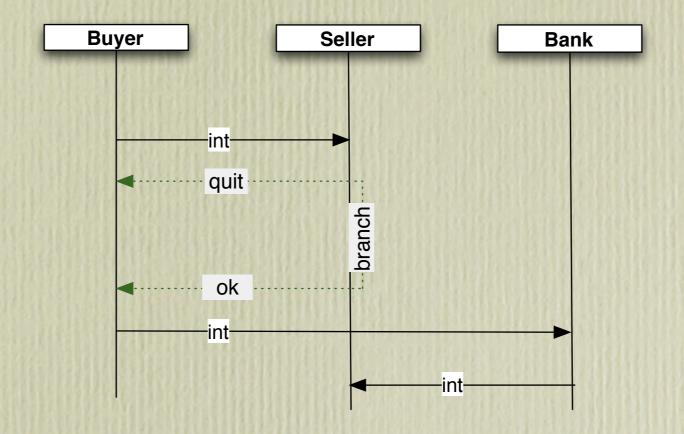
RUNTIME VALIDATION



Tzu-Chun Chen, Laura Bocchi, Pierre-Malo Denielou, Kohei Honda, Nobuko Yoshida **Distributed Monitoring for Multiparty Session Enforcement** http://www.eecs.qmul.ac.uk/~tcchen/monitoring_sessions.html

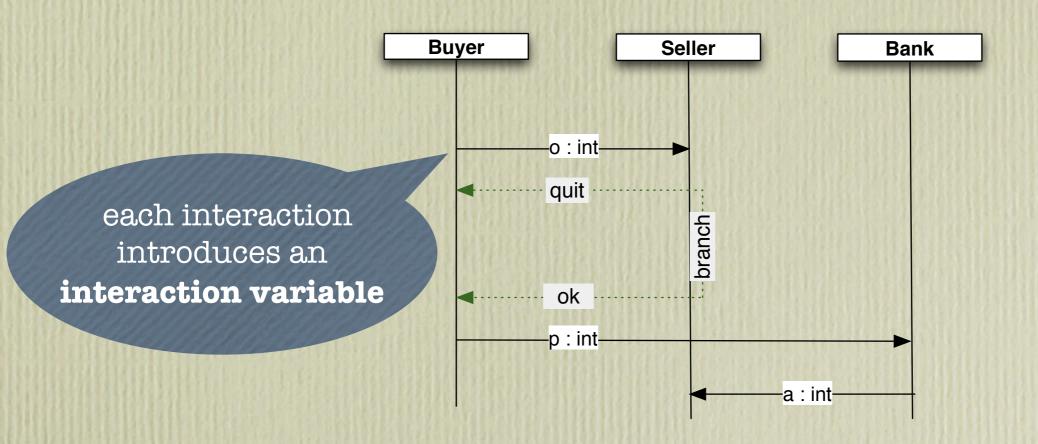
- From recent collaboration with Ocean Observation Initiative (OOI) on large scale distributed systems
- Unsafe endpoints in multiple administrative domains.
- Use previous theory to achieve runtime enforcement

GLOBAL ASSERTIONS



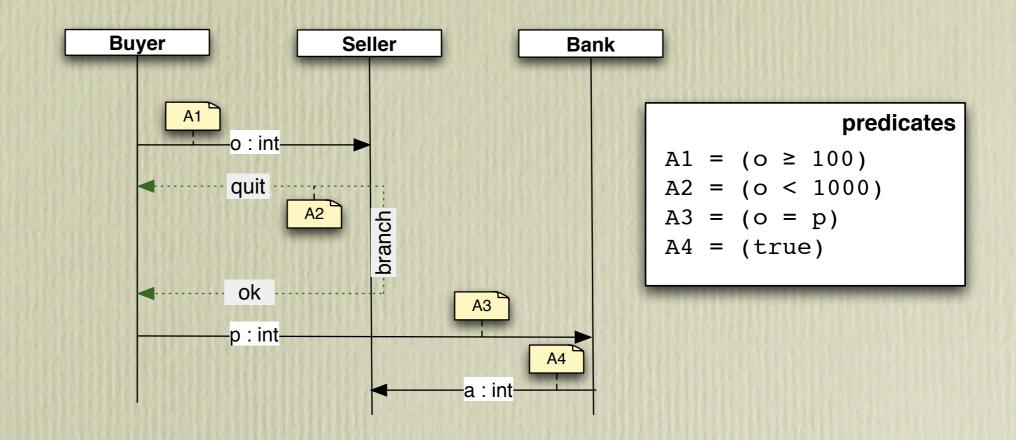
```
egin{aligned} 	ext{Buyer} &
ightarrow 	ext{Seller}: k_1(	ext{Int}). \ 	ext{Seller} &
ightarrow 	ext{Buyer}: k_2\{	ext{quit}: 	ext{End}, \ 	ext{ok}: 	ext{Buyer} &
ightarrow 	ext{Bank}: k_3(	ext{Int}). \ 	ext{Bank} &
ightarrow 	ext{Seller}: k_4(	ext{Int}) \ \end{cases}
```

GLOBAL ASSERTIONS



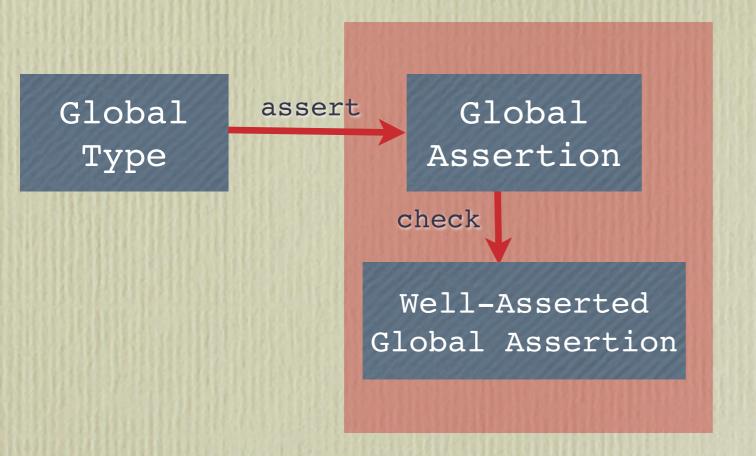
```
\begin{array}{c} \mathtt{Buyer} \to \mathtt{Seller} : k_1({\color{red}o} : \mathtt{Int}). \\ \mathtt{Seller} \to \mathtt{Buyer} : k_2\{\mathtt{quit} : \mathtt{End}, \\ \mathtt{ok} : \mathtt{Buyer} \to \mathtt{Bank} : k_3({\color{red}p} : \mathtt{Int}). \\ \mathtt{Bank} \to \mathtt{Seller} : k_4({\color{red}a} : \mathtt{Int}) \end{array}
```

GLOBAL ASSERTIONS



```
\begin{array}{c} \mathtt{Buyer} \to \mathtt{Seller} : k_1(o:\mathtt{Int})\{A_1\}. \\ \mathtt{Seller} \to \mathtt{Buyer} : k_2\{\{A_2\}\ \mathtt{quit} : \mathtt{End}, \\ \{\mathit{true}\}\ \mathtt{ok} : \mathtt{Buyer} \to \mathtt{Bank} : k_3(p:\mathtt{Int})\{A_3\}. \\ \mathtt{Bank} \to \mathtt{Seller} : k_4(a:\mathtt{Int})\{A_4\} \\ \} \end{array}
```

CONSISTENCY CHECK



When is a global assertion well designed?

HISTORY SENSITIVITY

"an interaction predicate can only contain those interaction variables that are known to its sender"

```
\begin{array}{lll} \textbf{Alice} \rightarrow \textbf{Bob}: (u: \texttt{Int}) \{ \textbf{true} \}. & \textbf{Alice Bob Carol} \\ \textbf{X} & \texttt{Bob} \rightarrow \texttt{Carol}: (v: \texttt{Int}) \{ \textbf{true} \}. & u & u \\ & \texttt{Carol} \rightarrow \texttt{Alice}: (z: \texttt{Int}) \{ z > u \} & v & v \\ \end{array}
```

 $\begin{array}{l} \texttt{Alice} \to \texttt{Bob} : (u: \texttt{Int}) \{ \textbf{true} \}. \\ \\ \checkmark \quad \texttt{Bob} \to \texttt{Carol} : (v: \texttt{Int}) \{ v > u \}. \\ \\ \texttt{Carol} \to \texttt{Alice} : (z: \texttt{Int}) \{ z > v \}. \\ \end{array}$

Carol cannot guarantee z>u since she does not know u

TEMPORAL SATISFIABILITY

"a process can always find a valid forward path at each interaction point until it meets the end"

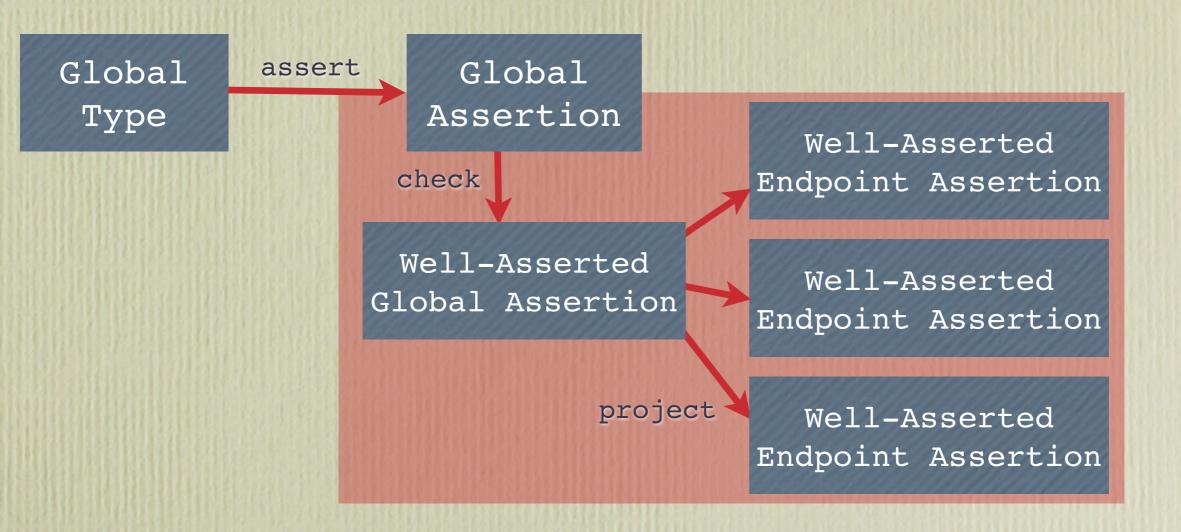
```
Alice \rightarrow Bob : (v: Int)\{v>10\}. Bob \rightarrow Alice : (z: Int)\{z< v \land z>10\}.
```

```
 \begin{array}{c} \text{Alice} \rightarrow \text{Bob}: (v: \text{Int})\{v>12\}. \\ \text{Bob} \rightarrow \text{Alice}: (z: \text{Int})\{z < v \ \land \ z>10\}. \end{array}
```

Had Alice
chosen v=11,
Carol could not find
a value for z s.t.
z<11 and z>10

- Well-assertedness = History Seisitivity + Temporal Satisfiability
 - is decidable (as long as the logic is)
 - we provide design-time checker

PROJECT



How to project obligations and guarantees onto the endpoints?

ENDPOINT ASSERTIONS

Global assertions

```
	ext{p} 
ightarrow 	ext{p}' : k(oldsymbol{v}: 	ext{S}) \{A\}. \mathcal{G}
	ext{p} 
ightarrow 	ext{p}' : k\{\{A_i\}l_i: \mathcal{G}_i\}_{i \in I}
\mu 	ext{t} \langle oldsymbol{e} \rangle (oldsymbol{v}: 	ext{S}) \{A\}. \mathcal{G}
	ext{t} \langle oldsymbol{e} \rangle
	ext{\mathcal{G}}, \mathcal{G}'
End
```

Endpoint assertions

$$k!(v:\mathtt{S})\{A\};\mathcal{T}$$
 $k?(v:\mathtt{S})\{A\};\mathcal{T}$
 $k \oplus \{\{A_i\}l_i:\mathcal{T}_i\}_{i \in I}$
 $k\&\{\{A_i\}l_i:\mathcal{T}_i\}_{i \in I}$
 $\mu\mathsf{t}\langle e\rangle(v:\mathtt{S})\{A\}.\mathcal{T}$
 $\mathsf{t}\langle e\rangle$
End

PROJECTIONS

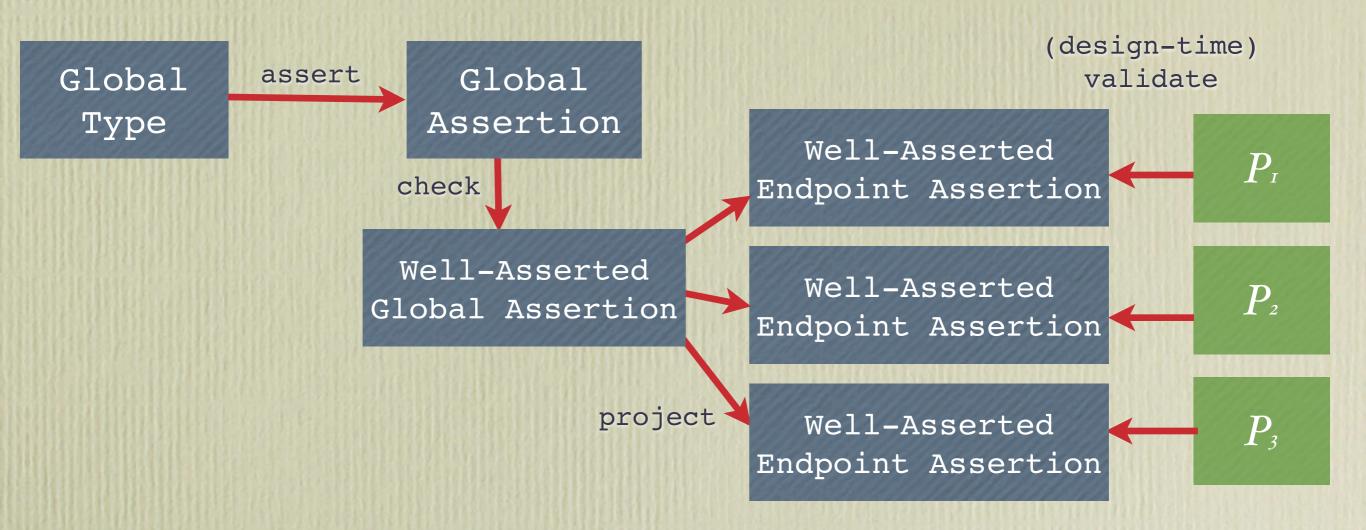
```
\begin{array}{l} \mathtt{User} \to \mathtt{Agent} : k_1(c1: \mathtt{Command}) \{c1 \neq \mathtt{switch} - \mathtt{off}\}. \\ \mathtt{Agent} \to \mathtt{Instrument} : k_2(c2: \mathtt{Command}) \{c2 = c1\} \end{array}
```

• A too naive projection on **Instrument**:

$$k_2?(c2: \texttt{Command})\{c2=c1\}$$

- $k_2?(c2: \mathtt{Command})\{\exists c1.(c1 \neq \mathtt{switch} \mathtt{off}) \land (c2 = c1)\}$
- We want to give **stronger preconditions** to prevent defensive programming
- We do not reveal the exact values exchanged between third parties

STATIC VALIDATION



How to ensure that a process satisfies a contract expressed as an assertion?

ASSERTED PROCESSES

Programs Run-time processes $P_{rt} ::= P$ $P ::= \overline{a}[2..n](\tilde{s}).P$ if e then P else Q conditional request $a[p](\tilde{s}).P$ $(v\tilde{s})P_{rt}$ $s \triangleleft \{A\}l;P$ accept select (va)P $|s \triangleright \{\{A_i\}l_i: P_i\}_{i \in I}$ $s:\tilde{h}$ hide branch $s!\langle e\rangle(v)\{A\};P$ |P|Qsend parallel errH $s?(v)\{A\};P$ $|\mu X\langle e\tilde{t}\rangle(v\tilde{s}).P$ receive rec def errT $|s! \langle \langle \tilde{t} \rangle \rangle \langle \tilde{v} \rangle \langle A \rangle; P$ $|X\langle e\tilde{s}\rangle$ del-trw rec call $s?((\tilde{v}))\{A\};P$ 0 del-cth idle

errH notifies a violation in a send/select

errT notifies a violation in a receive/branch

Receive with no violation

$$s?(v)\{v \ge 10\}; P \mid s: 10 \cdot \tilde{h} \to P[10/v] \mid s: \tilde{h}$$

Receive with violation

$$s?(v)\{v \geq 10\}; P \mid s:1 \cdot \tilde{h} \rightarrow \texttt{errT} \mid s:\tilde{h}$$

VALIDATION RULES

```
\begin{array}{lll} C ::= \mbox{true} & | \ C \wedge A & \mbox{(assertion environment)} \\ \Gamma ::= \varnothing & | \ \Gamma, a : G \ | \ \Gamma, x : (\tilde{v} : \tilde{s}) \ L_1@p_1 ... \ L_n@p_n \ \mbox{(typing environment)} \\ \Delta ::= \varnothing & | \ \Delta, \tilde{s} : T@p & \mbox{(assignment environment)} \end{array}
```

$$\mathcal{C};\Gamma\vdash P
ightarrow\Delta$$
 P is validated against Δ and Γ

$$\frac{\mathcal{C} \wedge A; \Gamma \qquad \vdash P \ \triangleright \ \Delta, s \colon T \ @ \ \mathbf{p}}{\mathcal{C}; \Gamma \vdash s_k?(v)\{A\}; P \triangleright \Delta, \ \tilde{s} \colon k?(v \colon S)\{A\}; T \ @ \ \mathbf{p}} \qquad [\mathsf{Rcv}]$$

$$\frac{\mathcal{C} \subset A[e/v] \quad \mathcal{C}; \Gamma \vdash P[e/v] \ \triangleright \ \Delta, \tilde{s} \colon T[e/v] \ @ \ \mathbf{p}}{\mathcal{C}; \Gamma \vdash s_k! \langle e \rangle(v)\{A\}; P \ \triangleright \ \Delta, \tilde{s} \colon k!(v \colon S)\{A\}; T \ @ \ \mathbf{p}} \qquad [\mathsf{Snd}]$$

SOUNDNESS & COMPLETENESS

Theorem (Soundness of Validation Rules)

Let P be a closed program. Then $\Gamma \vdash P \triangleright \Delta$ implies $\Gamma \models P \triangleright \Delta$

P conditionally simulates Δ and Γ (the simulation only holds for valid inputs)

Theorem (Completeness of Validation Rules)

For each closed visible program P, if $\Gamma \models P \triangleright \Delta$ then $\Gamma \vdash P \triangleright \Delta$

Theorem (Error Freedom) Let P be a closed program.

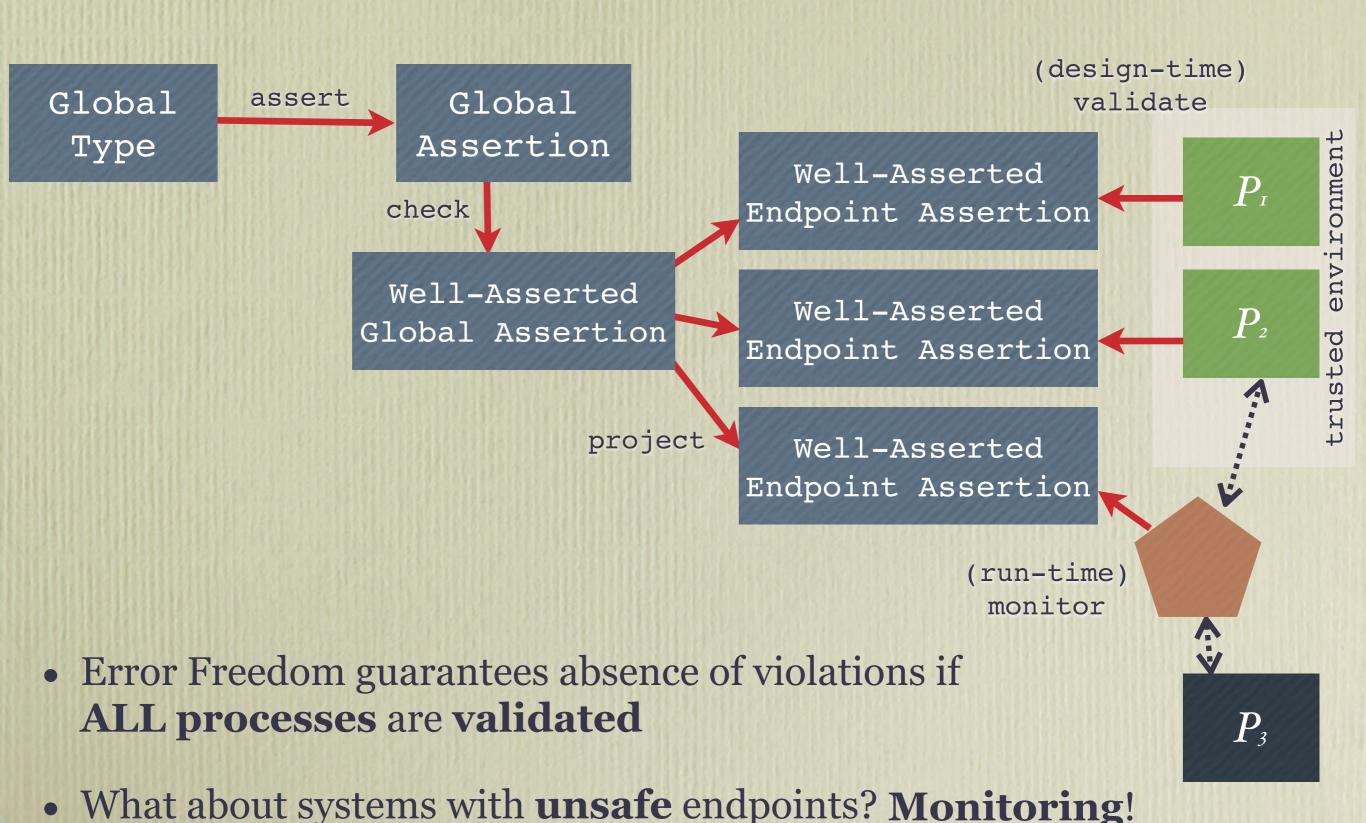
Suppose

1.
$$\Gamma \vdash P \triangleright \Delta$$
,

2. $P \xrightarrow{\ell_1..\ell_n} P'$ such that $\langle \Gamma, \Delta \rangle$ allows $\ell_1..\ell_n$.

Then P' contains neither errH nor errT.

RUNTIME VALIDATION



00I (Ocean Observation Initiative)

- Enabling environmental science observatories with persistent and interactive capabilities
- OOI cyberinfrastructure (OOI CI) based on **loosely coupled** distributed services and agents (e.g., seafloor instruments, on-shore research stations) communicating through a **common messaging infrastructure**.
- Systems are large scale, distributed, multi-organizational
- Applications built form application-level protocols
- Need for global safety ensurance by local validation with possibly unsafe endpoints

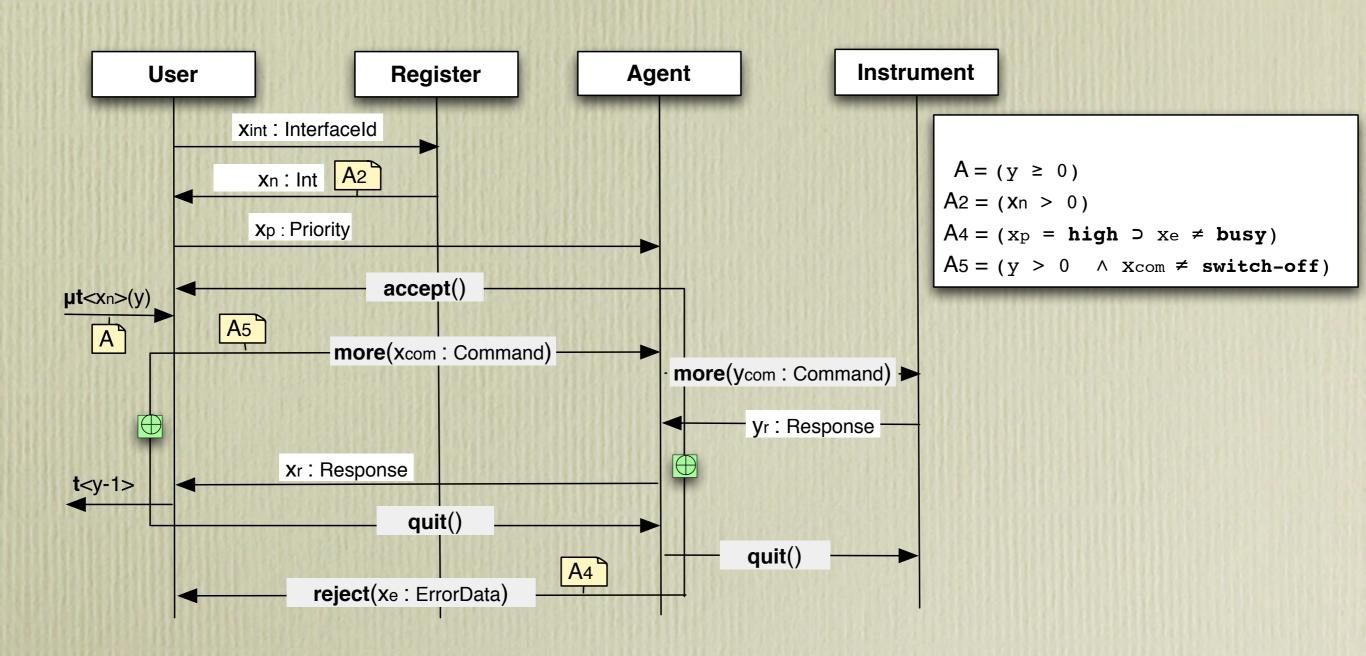


OOI (Ocean Observatories Initiaitve)

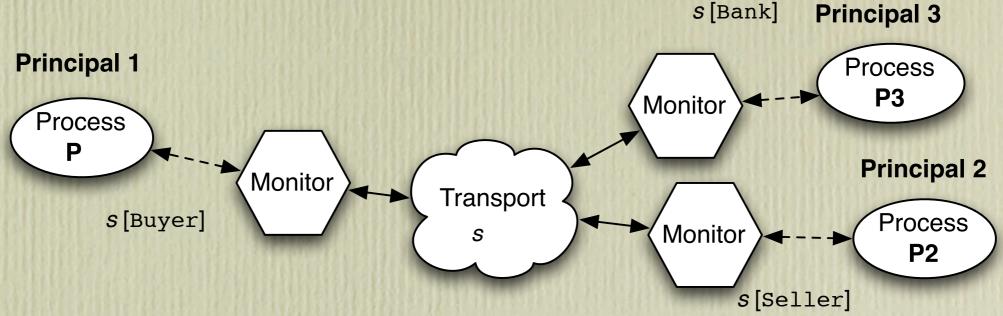
http://www.oceanleadership.org/programs-andpartnerships/ocean-observing/ooi/



INSTRUMENT COMMAND



THE ARCHITECTURE



$$\mathcal{T} = \text{Buyer}!k(o: \text{Int})\{o \geq 100\}.\mathcal{T}'$$

Process Pi

$$P = s_k! \langle 80 \rangle (o).P' \mid s[\mathtt{Buyer}] : \emptyset$$

$$\downarrow \tau$$

$$P_1 = P' \mid s[\mathtt{Buyer}] : \langle \mathtt{Buyer}, \mathtt{Seller}, \langle 80 \rangle \rangle$$

$$\downarrow s[\mathtt{Buyer}, \mathtt{Seller}] \langle 80 \rangle$$

Monitor

$$\mathcal{M} = s[\mathtt{Buyer}]^{ullet} : \mathcal{T}$$

$$\downarrow \mathcal{T}$$

$$\mathcal{M} = s[\mathtt{Buyer}]^{ullet} : \mathcal{T}$$

$$\downarrow s[\mathtt{Buyer}, \mathtt{Seller}] \langle 80 \rangle$$

$$P_2 = P'[80/o] \mid s[\texttt{Buyer}] : \emptyset$$

$$\mathcal{M} \vdash v : S, A\{n/v\} \downarrow \text{true}, \mathcal{T} \curvearrowright p_2!(v : S)\{A\}; \mathcal{T}'$$

 $\mathcal{M}, s[p_1]^{\bullet} : \mathcal{T} \xrightarrow{s[p_1, p_2]!(n)} \mathcal{M}, s[p_1]^{\bullet} : \mathcal{T}\{n/v\}$

PROPERTIES

- Local/global conformance: a monitored process well- behaves and coherence is preserved in a network
- Local/global transparency: monitors do not alter well-behaved interactions
- Session fidelity: the interactions of a network are step-by-step conform to the corresponding global types

PROPERTIES

Theorem (Local Conformance) $\mathcal{M} \models \mathcal{M}[P]$ for all \mathcal{M} and PTheorem (Global Conformance) $N \stackrel{\ell}{\longrightarrow}_g N'$ with N coherent implies N' is coherent

Theorem (Local Transparency) If $\mathcal{M} \models \mathcal{M}^{\circ}[P]$ then $\mathcal{M} \models \mathcal{M}^{\circ}[P] \sim \mathcal{M}[P]$

Theorem (Global Transparency) Suppose N is coherent and locally conformant. Then $N \sim \texttt{erase}(N)$

Theorem (Session Fidelity) If $\mathcal{E} \vdash N$ and $N \stackrel{\ell}{\longrightarrow}_g N'$ then $\mathcal{E} \stackrel{\ell}{\longrightarrow}_g \mathcal{E}'$ such that $\mathcal{E}' \vdash N'$

CONCLUSIONS

• We enabled DbC for distributed interactions trough the elaboration of MPSTs with logic formulae

Design time

- Local validation of global safety
- Sound+relatively complete validation system
- Effectiveness

Runtime

- Local enforcement of global safety with unsafe endpoints
- Prototype: framework for interoperable processes (Scala, Java, OCaml)
- Efficiency

RELATED WORK

HML

- M. Berger, K. Honda, and N. Yoshida. Completeness and logical full abstraction for modal logics for the typed pi-calculus. ICALP 2008
- M. Dam. Proof systems for pi-calculus logics. In Logic for Concurrency and Synchronisation, Trends in Logic, 2003

Contracts

- L. Acciai and M. Borale. A type system for client progress in a service-oriented calculus. In Concurrency, Graphs and Models, 2008
- M. Bravetti and G. Zavattaro. A foundational theory of contracts for multi-party service composition. Fundamenta Informaticae, XX:1–28, 2008
- L. Caires and H. T. Vieira. Conversation types. ESOP 2009
- G. Castagna and L. Padovani. Contracts for mobile processes. CONCUR 2009
- K. Honda, N. Yoshida, and M. Carbone. Multiparty asynchronous session types. POPL 2008.

RELATED WORK

Assertions for functional programming

- S. Peyton Jones et al. Composing contracts: an adventure in financial engineering. ICFP 2000.
- D. Xu and S. Peyton Jones. Static contract checking for Haskell. POPL 2009

DBC

 P. Nienaltowski, B. Meyer, and J. S. Ostroff. Contracts for concurrency. Form. Asp. Comput., 21(4):305-318, 2009.

Corresponding assertions, refinement/dependent types

- E. Bonelli, A. Compagnoni, and E. Gunter. Correspondence assertions for process synchronization in concurrent communications. JFC, 15(2):219-247, 2005
- K. Bhargavan, C. Fournet, and A. D. Gordon. Modular verification of security protocol code by typing. POPL 2010.
- T. Freeman and F. Pfenning. Refinement types for ML. SIGPLAN Not., 26(6):268-277, 1991.
- H. Xi and F. Pfenning. Dependent types in practical programming. POPL 1999.